## Package 'literanger'

July 22, 2025

Title Fast Serializable Random Forests Based on 'ranger'

Version 0.2.0

Description An updated implementation of R package 'ranger' by Wright et al, (2017) <doi:10.18637/jss.v077.i01> for training and predicting from random forests, particularly suited to high-dimensional data, and for embedding in 'Multiple Imputation by Chained Equations' (MICE) by van Buuren (2007) <doi:10.1177/0962280206074463>. Ensembles of classification and regression trees are currently supported. Sparse data of class 'dgCMatrix' (R package 'Matrix') can be directly analyzed. Conventional bagged predictions are available alongside an efficient prediction for MICE via the algorithm proposed by Doove et al (2014) <doi:10.1016/j.csda.2013.10.025>. Trained forests can be written to and read from storage. Survival and probability forests are not supported in the update, nor is data of class 'gwaa.data' (R package 'GenABEL'); use the original 'ranger' package for these analyses.

```
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## **Description**

Copy the trees from two forests to construct a new random forest object.

## Usage

```
## S3 method for class 'literanger'
merge(x, y, save_memory = FALSE, verbose = FALSE, ...)
```

## **Arguments**

X	A trained random forest literanger object.
У	A trained random forest literanger object.
save_memory	Ignored, only used in training (perhaps future use).
verbose	Print additional debug output from merging procedure.
	Ignored.

## **Details**

This is a naive implementation of a random-forest merge procedure. The trees from each forest are copied and then used to construct a new random forest object.

Classification and regression forests cannot be mixed together. The response type and levels (if a factor) must match.

The predictor names, type, and levels (if a factor) must match, although they can be provided in a different order.

There is no requirement that the forests were trained on the same data; just the same data types.

Internally, literanger will 'map' any differences in the order of the predictors (or its internal representation of response values) between x and y so that the result has the same ordering as x.

The out-of-bag error is discarded, along with the training information, as the result is a *merged* forest (not a *trained* one). It is up to you, the user, to keep track of the training parameters of x and y if they are still of use to you.

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#### Value

Object of class literanger with a *copy* of the trees from x and y held in the cpp11\_ptr item, and the following items:

```
tree_type The type of tree in the forest, either 'classification' or 'regression'.
```

n\_tree The sum of the number of trees in x and y.

training An empty list; as the result is due to merging, not training.

predictors A list with the names of the predictors, the names of the unordered predictors, and the levels of any factors.

response The levels and type indicator (e.g. logical, factor, etc) of the response.

oob\_error NULL, as there is no consensus on how to merge OOB estimates

cpp11\_ptr An external pointer to the merged forest. DO NOT MODIFY.

#### Author(s)

stephematician stephematician@gmail.com.

## **Examples**

```
## Train two classification forests
train_idx <- sample(nrow(iris), 2/3 * nrow(iris))
iris_train <- iris[train_idx, ]
iris_test <- iris[-train_idx, ]
lr_x <- train(data=iris_train, response_name="Species", n_tree=32)
lr_y <- train(data=iris_train, response_name="Species", n_tree=32)
## Merge
lr_iris <- merge(lr_x, lr_y)
pred_iris <- predict(lr_iris, newdata=iris_test)
table(iris_test$Species, pred_iris$values)</pre>
```

predict.literanger

Literanger prediction

## **Description**

'literanger' provides different types of prediction that may be used in multiple imputation algorithms with random forests. The usual prediction is the 'bagged' prediction, the most frequent value (or the mean) of the in-bag samples in a terminal node. Doove et al (2014) propose a prediction that better matches the predictive distribution as needed for multiple imputation; take a random draw from the observations in the terminal node from a randomly drawn tree in the forest for each predicted value needed. Alternatively, the usual most-frequent-value or mean of the in-bag responses can be used as in missForest (Stekhoven et al, 2014) or miceRanger https://cran.r-project.org/package=miceRanger and missRanger https://cran.r-project.org/package=missRanger.

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## Usage

```
## $3 method for class 'literanger'
predict(
  object,
  newdata = NULL,
  prediction_type = c("bagged", "inbag", "nodes"),
  seed = 1L + sample.int(n = .Machine$integer.max - 1L, size = 1),
  n_thread = 0,
  verbose = FALSE,
  ...
)
```

## **Arguments**

object A trained random forest literanger object.

newdata Data of class data.frame, matrix, or dgCMatrix (Matrix), for the latter two;

must have column names; all predictors named in object\$predictor\_names

must be present.

prediction\_type

Name of the prediction algorithm; "bagged" is the most-frequent value among in-bag samples for classification, or the mean of in-bag responses for regression; "inbag" predicts by drawing one in-bag response from a random tree for each row; "nodes" returns the node keys (ids) of the terminal node from every tree for

each row.

seed Random seed, an integer between 1 and .Machine\$integer.max. Default gen-

erates the seed from R, set to 0 to ignore the R seed and use a C++ std::random\_device.

n\_thread Number of threads. Default is determined by system, typically the number of

cores.

verbose Show computation status and estimated runtime.

... Ignored.

## Details

Forests trained by literanger retain information about the in-bag responses in each terminal node, thus facilitating efficient predictions within a variation on multiple imputation proposed by Doove et al (2014). This type of prediction can be selected by setting prediction\_type="inbag", or the usual prediction for classification and regression forests, the most-frequent-value and mean of in bag samples respectively, is given by setting prediction\_type="bagged".

A list is returned. The values item contains the predicted classes or values (classification and regression forests, respectively). Factor levels are returned as factors with the levels as per the original training data.

Compared to the original package ranger, literanger excludes certain features:

- Probability, survival, and quantile regression forests.
- Support for class gwaa.data.
- Standard error estimation.

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#### Value

Object of class literanger\_prediction with elements:

values Predicted (drawn) classes/value for classification and regression (when prediction type is not nodes).

```
tree_type Number of trees.
```

seed The seed supplied to the C++ library.

nodes When prediction type is nodes: a matrix of terminal node identifiers, with each row being a prediction and each column being a tree.

## Author(s)

stephematician stephematician@gmail.com, Marvin N Wright (original ranger package)

#### References

- Doove, L. L., Van Buuren, S., & Dusseldorp, E. (2014). Recursive partitioning for missing data imputation in the presence of interaction effects. *Computational Statistics & Data Analysis*, 72, 92-104. doi:10.1016/j.csda.2013.10.025.
- Stekhoven, D.J. and Buehlmann, P. (2012). MissForest–non-parametric missing value imputation for mixed-type data. *Bioinformatics*, 28(1), 112-118. doi:10.1093/bioinformatics/btr597.
- Wright, M. N., & Ziegler, A. (2017a). ranger: A Fast Implementation of Random Forests for High Dimensional Data in C++ and R. *Journal of Statistical Software*, 77, 1-17. doi:10.18637/jss.v077.i01.

#### See Also

train

## **Examples**

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De-serialize random forest

## **Description**

Read the random forest from a file or connection using light-weight serialization for C++ objects.

## Usage

```
read_literanger(file, verbose = FALSE, ...)
```

## **Arguments**

file A connection or the name of a file containing a serialized literanger object.

verbose Show additional serialization information (not implemented).

... Further arguments passed to readRDS().

## **Details**

This function uses 'cereal' light-weight serialization to read a literanger object (random forest) from a file or connection. The file is usually the result of a call to write\_literanger(). The random forest returned can be used for prediction immediately upon return, and does not require the original training data or training environment.

#### Value

A literanger random forest object

## Author(s)

stephematician <stephematician@gmail.com

## See Also

```
write_literanger() readRDS
```

train

Train forest using ranger for multiple imputation algorithms.

## **Description**

'literanger' trains random forests for use in multiple imputation problems via an adaptation of the 'ranger' R package. ranger is a fast implementation of random forests (Breiman, 2001) or recursive partitioning, particularly suited for high dimensional data (Wright et al, 2017a). literanger supports prediction used in algorithms such as "Multiple Imputation via Chained Equations" (Van Buuren, 2007).

## Usage

```
train(
  data = NULL,
  response_name = character(),
 predictor_names = character(),
  x = NULL,
  y = NULL,
  case_weights = numeric(),
  classification = NULL,
  n_{tree} = 10,
  replace = TRUE,
  sample_fraction = ifelse(replace, 1, 0.632),
  n_{try} = NULL
  draw_predictor_weights = numeric(),
  names_of_always_draw = character(),
  split_rule = NULL,
 max_depth = 0,
 min_split_n_sample = 0,
 min_leaf_n_sample = 0,
  unordered_predictors = NULL,
  response_weights = numeric(),
  n_random_split = 1,
  alpha = 0.5,
 min_prop = 0.1,
  seed = 1L + sample.int(n = .Machine$integer.max - 1L, size = 1),
  save_memory = FALSE,
  n_{thread} = 0,
  verbose = FALSE
)
```

#### **Arguments**

data Training data of class data.frame, matrix, or dgCMatrix (Matrix), for the latter two; must have column names.

response\_name Name of response (dependent) variable if data was provided.

predictor\_names

y

Names of predictor (independent) variables if data was provided; default is all variables that are not the response.

x Predictor data (independent variables), alternative interface to data and response\_name.

Response vector (dependent variable), alternative interface to data and response\_name.

case\_weights Weights for sampling of training observations. Observations with larger weights

will be selected with higher probability in the bootstrap (or sub-sampled) sam-

ples for each tree.

classification Set to TRUE to grow a classification forest if the response is numeric (including

if data is a matrix), else, a regression forest is grown.

n\_tree Number of trees (default 10).

replace Sample with replacement to train each tree.

sample\_fraction

n\_try

Fraction of observations to sample to train each tree. Default is 1 for sampling with replacement and 0.632 for sampling without replacement. For classification, this can be a vector of class-specific values.

tion, this can be a vector of class-specific values.

Number of variables (predictors) to draw that are candidates for splitting each node by. Default is the (rounded down) square root of the number of predictors. Alternatively, a single argument function returning an integer, given the number of predictors.

draw\_predictor\_weights

For predictor-drawing weights shared by all trees; a numeric vector of *non-negative* weights for each predictor. For tree-specific predictor-drawing weights; a list of size n\_tree containing (non-negative) vectors with length equal to the number of predictors.

names\_of\_always\_draw

Character vector with predictor (variable) names to be selected *in addition* to the  $n_{try}$  predictors drawn as candidates to split by.

split\_rule Splitting rule. For classification estimation "gini", "extratrees" or "hellinger" with default "gini". For regression "variance", "extratrees", "maxstat" or "beta"

with default "variance".

max\_depth Maximal tree depth. A value of NULL or 0 (the default) corresponds to unlimited depth. I to tree extraores (1 pulls are tree)

ited depth, 1 to tree stumps (1 split per tree).

min\_split\_n\_sample

Minimal number of in-bag samples a node must have in order to be split. Default 1 for classification and 5 for regression.

min\_leaf\_n\_sample

Minimum number of in-bag samples in a leaf node.

unordered\_predictors

Handling of unordered factor predictors. One of "ignore", "order" and "partition". For the "extratrees" splitting rule the default is "partition" for all other splitting rules "ignore".

response\_weights

Classification only: Weights for the response classes (in order of the factor levels) in the splitting rule e.g. cost-sensitive learning. Weights are also used by each tree to determine majority vote.

n\_random\_split "extratrees" split metric only: Number of random splits to consider for each

candidate splitting variable, default is 1.

alpha "maxstat" splitting rule only: Significance threshold to allow splitting, default is

0.5, must be in the interval (0,1].

min\_prop "maxstat" splitting rule only: Lower quantile of covariate distribution to be con-

sidered for splitting, default is 0.1, must be in the interval [0, 0.5].

seed Random seed, an integer between 1 and .Machine\$integer.max. Default gen-

erates the seed from R, set to 0 to ignore the R seed and use a C++ std::random\_device.

save\_memory Use memory saving (but slower) splitting mode. Warning: This option slows

down the tree growing, use only if you encounter memory problems.

Number of threads. Default is determined by system, typically the number of

cores.

verbose Show computation status and estimated runtime.

#### **Details**

n\_thread

literanger trains classification and regression forests using the original Random Forest (Breiman, 2001) or extremely randomized trees (Geurts et al, 2006) algorithms. The trained forest retains information about the in-bag responses in each terminal node, thus facilitating a variation on the algorithm for multiple imputation with random forests proposed by Doove et al (2014). This algorithm should match the predictive distribution more closely than using predictive mean matching.

The default split metric for classification trees is the Gini impurity, which can be extended to use the extra-randomized trees rule (Geurts et al, 2006). For binary responses, the Hellinger distance metric may be used instead (Cieslak et al, 2012).

The default split metric for regression trees is the estimated variance, which can be extended to include the extra-randomized trees rule, too. Alternatively, the beta log-likelihood (Wright et al, 2017b) or maximally selected rank statistics (Wright et al, 2019) are available.

When the data and response\_name arguments are supplied the response variable is identified by its corresponding column name. The type of response may be used to determine the type of tree. If the response is a factor then classification trees are used. If the response is numeric then regression trees are used. The classification argument can be used to override the default tree type when the response is numeric. Alternatively, use x and y arguments to specify response and predictor; this can avoid conversions and save memory. If memory usage issues persist, consider setting save\_memory=TRUE but be aware that this option slows down the tree growing.

The min\_split\_n\_sample rule can be used to control the minimum number of in-bag samples required to split a node; thus, as in the original algorithm, nodes with fewer samples than min\_split\_n\_sample are possible. To put a floor under the number of samples per node, the min\_leaf\_n\_sample argument is used.

When drawing candidate predictors for splitting a node on, the predictors identified by names\_of\_always\_draw are included *in addition* to the n\_try predictors that are randomly drawn. Another way to modify the way predictors are selected is via the draw\_predictor\_weights argument, which are normalised and interpreted as probabilities when drawing candidates. The weights are assigned *in the order they appear in the data*. Weights assigned by draw\_predictor\_weights to variables in names\_of\_always\_draw are ignored. The usage of draw\_predictor\_weights can increase the computation times for large forests.

Unordered-factor predictors can be handled in 3 different ways by using unordered\_predictors:

- For "ignore" all factors are regarded ordered;
- For "partition" all possible 2-partitions are considered for splitting.
- For "order" and 2-class classification the factor levels are ordered by their proportion falling in the second class, for regression by their mean response, as described in Hastie et al. (2009), chapter 9.2.4. For multi-class classification the factor levels are ordered by the first principal component of the weighted covariance matrix of the contingency table (Coppersmith et al, 1999).

The use of "order" is recommended, as it computationally fast and can handle an unlimited number of factor levels. Note that the factors are only reordered once and not again in each split.

Compared to the original package ranger, literanger excludes certain features:

- Formula interface.
- Probability, survival, and quantile regression forests.
- Support for class gwaa.data.
- Measures of variable importance.
- Regularisation of importance.
- · Access to in-bag data via R.
- Support for user-specified hold-out data.

#### Value

Object of class literanger with elements:

tree\_type The type of tree in the forest, either classification or regression.

n\_tree The number of trees in the forest.

training The parameters for training that were passed at the time the forest was trained.

predictors A list with the names of the predictors, the names of the unordered predictors, and the levels of any factors.

response The levels and type indicator (e.g. logical, factor, etc) of the response.

oob\_error The misclassification rate or the mean square error using out-of-bag samples.

cpp11\_ptr An external pointer to the trained forest. DO NOT MODIFY.

#### Author(s)

stephematician stephematician@gmail.com, Marvin N Wright (original ranger package)

#### References

- Breiman, L. (2001). Random forests. Machine Learning, 45, 5-32. doi:10.1023/A:1010933404324.
- Cieslak, D. A., Hoens, T. R., Chawla, N. V., & Kegelmeyer, W. P. (2012). Hellinger distance decision trees are robust and skew-insensitive. *Data Mining and Knowledge Discovery*, 24, 136-158. doi:10.1007/s1061801102221.
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Doove, L. L., Van Buuren, S., & Dusseldorp, E. (2014). Recursive partitioning for missing data imputation in the presence of interaction effects. *Computational Statistics & Data Analysis*, 72, 92-104. doi:10.1016/j.csda.2013.10.025.

- Geurts, P., Ernst, D., & Wehenkel, L. (2006). Extremely randomized trees. *Machine Learning*, 63, 3-42. doi:10.1007/s1099400662261.
- Hastie, T., Tibshirani, R., Friedman, J. H., & Friedman, J. H. (2009). The elements of statistical learning: data mining, inference, and prediction (Vol. 2). New York: Springer. doi:10.1007/9780387216065.
- Van Buuren, S. (2007). Multiple imputation of discrete and continuous data by fully conditional specification. *Statistical Methods in Medical Research*, 16(3), 219-242. doi:10.1177/0962280206074463.
- Weinhold, L., Schmid, M., Wright, M. N., & Berger, M. (2019). A random forest approach for modeling bounded outcomes. arXiv preprint, arXiv:1901.06211. doi:10.48550/arXiv.1901.06211.
- Wright, M. N., & Ziegler, A. (2017a). ranger: A Fast Implementation of Random Forests for High Dimensional Data in C++ and R. *Journal of Statistical Software*, 77, 1-17. doi:10.18637/jss.v077.i01.
- Wright, M. N., Dankowski, T., & Ziegler, A. (2017b). Unbiased split variable selection for random survival forests using maximally selected rank statistics. *Statistics in medicine*, 36(8), 1272-1284. doi:10.1002/sim.7212.

#### See Also

```
predict.literanger
```

## Examples

```
## Classification forest with default settings
train(data=iris, response_name="Species")

## Prediction
train_idx <- sample(nrow(iris), 2/3 * nrow(iris))
iris_train <- iris[train_idx, ]
iris_test <- iris[-train_idx, ]
lr_iris <- train(data=iris_train, response_name="Species")
pred_iris <- predict(lr_iris, newdata=iris_test)
table(iris_test$Species, pred_iris$values)</pre>
```

write\_literanger

Serialize random forest

## **Description**

Write a random forest to a file or connection using light-weight serialization for C++ objects.

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## Usage

```
write_literanger(object, file, verbose = FALSE, ...)
```

## **Arguments**

object A trained random forest literanger object.

file A connection or the name of the file where the literanger object will be saved.

verbose Show additional serialization information (not implemented).

... Further arguments passed to saveRDS().

#### **Details**

This function uses 'cereal' light-weight serialization to write a literanger object (random forest) to a file or connection. The file can be read in via read\_literanger() and used for prediction with no requirement for the original training data.

## Author(s)

stephematician stephematician@gmail.com

#### See Also

```
read_literanger() saveRDS
```

## **Examples**

```
## Classification forest
train_idx <- sample(nrow(iris), 2/3 * nrow(iris))
iris_train <- iris[ train_idx, ]
iris_test <- iris[-train_idx, ]
lr_iris <- train(data=iris_train, response_name="Species")
file <- tempfile()
write_literanger(lr_iris, file)
lr_copy <- read_literanger(file)
pred_bagged <- predict(lr_copy, newdata=iris_test, prediction_type="bagged")</pre>
```

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