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Title Iterative Proportional Fitting Algorithms for Nested Structures

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Description The Iterative Proportional Fitting (IPF) algorithm operates on count data. This package offers implementations for several algorithms that extend this to nested structures: 'parent' and 'child' items for both of which constraints can be provided. The fitting algorithms include Iterative Proportional Updating <https: //trid.trb.org/view/881554>, Hierarchical IPF <doi:10.3929/ethz-a-006620748>, Entropy Optimization <https://trid.trb.org/view/881144>, and Generalized Raking <doi:10.2307/2290793>. Additionally, a number of replication methods is also provided such as 'Truncate, replicate, sample' <doi:10.1016/j.compenvurbsys.2013.03.004>.

License GPL (>= 3)

URL https://mlfit.github.io/mlfit/, https://github.com/mlfit/mlfit

BugReports https://github.com/mlfit/mlfit/issues

Depends methods

Imports BB, dplyr, hms, kimisc, Matrix, plyr, tibble, forcats, rlang, utils, wrswoR, lifecycle

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mlfit: Iterative Proportional Fitting Algorithms for Nested Structures

Description

The Iterative Proportional Fitting (IPF) algorithm operates on count data. This package offers implementations for several algorithms that extend this to nested structures: 'parent' and 'child' items for both of which constraints can be provided. The fitting algorithms include Iterative Proportional Updating <https://trid.trb.org/view/881554>, Hierarchical IPF <doi:10.3929/ethz-a-006620748>, Entropy Optimization <https://trid.trb.org/view/881144>, and Generalized Raking <doi:10.2307/2290793>. Additionally, a number of replication methods is also provided such as 'Truncate, replicate, sample' <doi:10.1016/j.compenvurbsys.2013.03.004>.

Details

To use this package, you need to:

- 1. Specify your fitting problem with ml_problem()
- 2. Optionally, convert the fitting problem to a structure that can be processed by the algorithms with flatten_ml_fit_problem(); this is helpful if you want to run the same fitting problem with multiple algorithms and compare results.
- 3. Compute weights with one of the algorithms provided in this package with ml_fit() or one of the specialized functions
- 4. Analyze weights or residuals, e.g. with compute_margins()

Author(s)

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compute_margins

See Also

Useful links:

- https://mlfit.github.io/mlfit/
- https://github.com/mlfit/mlfit
- Report bugs at https://github.com/mlfit/mlfit/issues

compute_margins Compute margins for a weighting of a multi-level fitting problem

Description

These functions allows checking a fit in terms of the original input data.

Usage

compute_margins(ml_problem, weights, verbose = FALSE)

margin_to_df(controls, count = NULL, verbose = FALSE)

Arguments

ml_problem	A fitting problem created by ml_problem() or returned by flatten_ml_fit_problem().
weights	A vector with one entry per row of the original reference sample
verbose	If TRUE, print diagnostic output.
controls	Margins as returned by compute_margins or as passed to the controls parameter of ml_problem().
count	Name of control total column, autodetected by default.

Details

compute_margins() computes margins in the format used for the input controls (i.e., as expected by the controls parameter of the ml_problem() function), based on a reference sample and a weight vector.

margins_to_df() converts margins to a data frame for easier comparison.

Value

compute_margins() returns a named list with two components, individual and group. Each contains a list of margins as data.frames.

margins_to_df() returns a data frame with the following columns:

..control.type.. Type of the control total: either individual or group.

.. control.name.. Name of the control total, if exists.

...id.. Name of the control category.

.. count.. Count of the control category.

See Also

ml_fit()

Examples

```
path <- toy_example("Tiny")
problem <- readRDS(path)
fit <- ml_fit(ml_problem = problem, algorithm = "entropy_o")
margins <- compute_margins(problem, fit$weights)
margins
margin_to_df(problem$controls)
margin_to_df(margins)</pre>
```

dss

Calibrate sample weights

Description

Calibrate sample weights according to known marginal population totals. Based on initial sample weights, the so-called *g*-weights are computed by generalized raking procedures. The final sample weights need to be computed by multiplying the resulting *g*-weights with the initial sample weights.

Usage

```
dss(
    X,
    d,
    totals,
    q = NULL,
    method = c("raking", "linear", "logit"),
    bounds = NULL,
    maxit = 500,
    ginv = gginv(),
    tol = 1e-06,
    attributes = FALSE
)
```

Arguments

Х	a matrix of calibration variables.
d	a numeric vector giving the initial sample (or design) weights.
totals	a numeric vector of population totals corresponding to the calibration variables in X.
q	a numeric vector of positive values accounting for heteroscedasticity. Small values reduce the variation of the <i>g</i> -weights.

 logit method. The first value gives the lower bound (which must be smaller than or equal to 1) and the second value gives the upper bound (which must be larger than or equal to 1). If NULL, the bounds are set to c(0, 10). maxit a numeric value giving the maximum number of iterations. ginv a function that computes the Moore-Penrose generalized inverse (default: an optimized version of MASS::ginv()). In some cases it is possible to speed up the process by using a function that computes a "regular" matrix inverse such as {solve.default}. tol relative tolerance; convergence is achieved if the difference of all residuals (relative to the corresponding total) is smaller than this tolerance. attributes 	method	a character string specifying the calibration method to be used. Possible values are "linear" for the linear method, "raking" for the multiplicative method known as raking and "logit" for the logit method.
 ginv a function that computes the Moore-Penrose generalized inverse (default: an optimized version of MASS::ginv()). In some cases it is possible to speed up the process by using a function that computes a "regular" matrix inverse such as {solve.default}. tol relative tolerance; convergence is achieved if the difference of all residuals (relative to the corresponding total) is smaller than this tolerance. attributes should additional attributes (currently success, iterations, method and bound be added to the result? If FALSE (default), a warning is given if convergence 	bounds	a numeric vector of length two giving bounds for the g-weights to be used in the logit method. The first value gives the lower bound (which must be smaller than or equal to 1) and the second value gives the upper bound (which must be larger than or equal to 1). If NULL, the bounds are set to $c(0, 10)$.
 optimized version of MASS::ginv()). In some cases it is possible to speed up the process by using a function that computes a "regular" matrix inverse such as {solve.default}. tol relative tolerance; convergence is achieved if the difference of all residuals (relative to the corresponding total) is smaller than this tolerance. attributes should additional attributes (currently success, iterations, method and bound be added to the result? If FALSE (default), a warning is given if convergence 	maxit	a numeric value giving the maximum number of iterations.
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be added to the result? If FALSE (default), a warning is given if convergence	tol	relative tolerance; convergence is achieved if the difference of all residuals (rel- ative to the corresponding total) is smaller than this tolerance.
	attributes	should additional attributes (currently success, iterations, method and bounds) be added to the result? If FALSE (default), a warning is given if convergence within the given relative tolerance could not be achieved.

Value

A numeric vector containing the g-weights.

Note

This is a faster implementation of parts of sampling::calib() from package sampling. Note that the default calibration method is raking and that the truncated linear method is not yet implemented.

Author(s)

Andreas Alfons, with improvements by Kirill Müller

References

Deville, J.-C. and Särndal, C.-E. (1992) Calibration estimators in survey sampling. *Journal of the American Statistical Association*, **87**(418), 376–382.

Deville, J.-C., Särndal, C.-E. and Sautory, O. (1993) Generalized raking procedures in survey sampling. *Journal of the American Statistical Association*, **88**(423), 1013–1020.

Examples

```
obs <- 1000
vars <- 100
Xs <- matrix(runif(obs * vars), nrow = obs)
d <- runif(obs) / obs
totals <- rep(1, vars)
g <- dss(Xs, d, totals, method = "linear", ginv = solve)
g2 <- dss(Xs, d, totals, method = "raking")</pre>
```

```
flatten_ml_fit_problem
```

Return a flattened representation of a multi-level fitting problem instance

Description

This function transforms a multi-level fitting problem to a representation more suitable for applying the algorithms: A matrix with one row per controlled attribute and one column per household, a weight vector with one weight per household, and a control vector.

Usage

```
flatten_ml_fit_problem(
 ml_problem,
 model_matrix_type = c("combined", "separate"),
 verbose = FALSE
)
as_flat_ml_fit_problem(x, model_matrix_type = c("combined", "separate"), ...)
```

Arguments _

2	
ml_problem	A fitting problem created by ml_problem() or returned by flatten_ml_fit_problem().
<pre>model_matrix_ty</pre>	'pe
	Which model matrix building strategy to use? See details.
verbose	If TRUE, print diagnostic output.
х	An object
	Further parameters passed to the algorithm

Details

The standard way to build a model matrix (model_matrix = "combined") is to include intercepts and avoid repeating redundant attributes. A simpler model matrix specification, available via model_matrix = "separate", is suggested by Ye et al. (2009) and required for the ml_fit_ipu() implementation: Here, simply one column per target value is used, which results in a larger model matrix if more than one control is given.

Value

An object of classes flat_ml_fit_problem, essentially a named list.

See Also

ml_fit()

gginv

Examples

```
path <- toy_example("Tiny")
flat_problem <- flatten_ml_fit_problem(ml_problem = readRDS(path))
flat_problem
fit <- ml_fit_dss(flat_problem)
fit$flat_weights
fit$weights</pre>
```

gg1	nv

Generalized Inverse of a Matrix using a custom tolerance or SVD implementation

Description

The gginv function creates a function that calculates the Moore-Penrose generalized inverse of a matrix X using a fixed tolerance value and a custom implementation for computing the singular value decomposition.

Usage

gginv(tol = sqrt(.Machine\$double.eps), svd = base::svd)

Arguments

tol	A relative tolerance to detect zero singular values.
svd	A function that computes the singular value decomposition of a matrix

Details

The svd argument is expected to adhere to the interface of base::svd(). It will be called as svd(x) (with the nu and nv arguments unset) and is expected to return a named list with components d, u and v.

Value

A function that accepts one argument X that computes a MP generalized inverse matrix for it.

Author(s)

Adapted implementation from the MASS package.

See Also

MASS::ginv(), base::svd()

ml_fit

Description

These functions reweight a reference sample to match constraints given by aggregate controls.

ml_fit() accepts an algorithm as argument and calls the corresponding function. This is useful if the result of multiple algorithms are compared to each other.

Usage

```
ml_fit(
 ml_problem,
  algorithm = c("entropy_o", "dss", "ipu", "hipf"),
  verbose = FALSE,
  ...,
  tol = 1e-06
)
is_ml_fit(x)
## S3 method for class 'ml_fit'
format(x, ...)
## S3 method for class 'ml_fit'
print(x, ...)
ml_fit_dss(
 ml_problem,
 method = c("raking", "linear", "logit"),
  ginv = gginv(),
  tol = 1e-06,
  verbose = FALSE
)
ml_fit_entropy_o(
 ml_problem,
  verbose = FALSE,
  tol = 1e-06,
  dfsane_args = list()
)
ml_fit_hipf(
 ml_problem,
  diff_tol = 16 * .Machine$double.eps,
  tol = 1e-06,
```

```
maxiter = 2000,
verbose = FALSE
)
ml_fit_ipu(
  ml_problem,
  diff_tol = 16 * .Machine$double.eps,
  tol = 1e-06,
  maxiter = 2000,
  verbose = FALSE
)
```

Arguments

ml_problem	A fitting problem created by ml_problem() or returned by flatten_ml_fit_problem().
algorithm	Algorithm to use
verbose	If TRUE, print diagnostic output.
	Further parameters passed to the algorithm
tol	Tolerance, the algorithm has succeeded when all target values are reached within this tolerance.
х	An object
method	Calibration method, one of "raking" (default), "linear", or "logit"
ginv	Function that computes the Moore-Penrose pseudoinverse.
dfsane_args	Additional arguments (as a named list) passed to the BB::dfsane() function used internally for the optimization.
diff_tol	Tolerance, the algorithm stops when relative difference of control values be- tween iterations drops below this value
maxiter	Maximum number of iterations.

Value

All functions return an object of class ml_fit, which is a named list under the hood. The class matches the function called, e.g., the return value of the ml_fit_ipu function also is of class ml_fit_ipu.

All returned objects contain at least the following components, which can be accessed with \$ or [[:

- weights: Resulting weights, compatible to the original reference sample
- tol: The input tolerance
- iterations: The actual number of iterations required to obtain the result
- flat: The flattened fitting problem, see flatten_ml_fit_problem()
- flat_weights: Weights in terms of the flattened fitting problem
- residuals: Absolute residuals
- rel_residuals: Relative residuals
- success: Are the residuals within the tolerance?

is_ml_fit() returns a logical.

References

Deville, J.-C. and Särndal, C.-E. (1992) Calibration estimators in survey sampling. *Journal of the American Statistical Association*, **87** (418), 376–382.

Deville, J.-C., Särndal, C.-E. and Sautory, O. (1993) Generalized raking procedures in survey sampling. *Journal of the American Statistical Association*, **88** (423), 1013–1020.

Bar-Gera, H., Konduri, K. C., Sana, B., Ye, X., & Pendyala, R. M. (2009, January). Estimating survey weights with multiple constraints using entropy optimization methods. In 88th Annual Meeting of the Transportation Research Board, Washington, DC.

Müller, K. and Axhausen, K. W. (2011), Hierarchical IPF: Generating a synthetic population for Switzerland, paper presented at the 51st Congress of the European Regional Science Association, University of Barcelona, Barcelona.

Ye, X., K. Konduri, R. M. Pendyala, B. Sana and P. A. Waddell (2009) A methodology to match distributions of both household and person attributes in the generation of synthetic populations, paper presented at the *88th Annual Meeting of the Transportation Research Board*, Washington, D.C., January 2009.

See Also

```
dss(), gginv()
```

BB::dfsane()

Examples

```
path <- toy_example("Tiny")</pre>
fit <- ml_fit(ml_problem = readRDS(path), algorithm = "entropy_o")</pre>
fit
fit$weights
fit$tol
fit$iterations
fit$flat
fit$flat_weights
fit$residuals
fit$rel_residuals
fit$success
ml_fit_dss(ml_problem = readRDS(path))
ml_fit_dss(ml_problem = readRDS(path), ginv = solve)
ml_fit_entropy_o(ml_problem = readRDS(path))
ml_fit_hipf(ml_problem = readRDS(path))
ml_fit_ipu(ml_problem = readRDS(path))
```

ml_problem

Create an instance of a fitting problem

ml_problem

Description

The ml_problem() function is the first step for fitting a reference sample to known control totals with mlfit. All algorithms (see ml_fit()) expect an object created by this function (or optionally processed with flatten_ml_fit_problem()).

The special_field_names() function is useful for the field_names argument to ml_problem.

Usage

```
ml_problem(
  ref_sample,
  controls = list(individual = individual_controls, group = group_controls),
  field_names,
  individual_controls,
  group_controls,
 prior_weights = NULL,
  geo_hierarchy = NULL
)
is_ml_problem(x)
## S3 method for class 'ml_problem'
format(x, ...)
## S3 method for class 'ml_problem'
print(x, ...)
special_field_names(
  groupId,
  individualId,
  individualsPerGroup = NULL,
  count = NULL,
  zone = NULL,
  region = NULL
```

)

Arguments

ref_sample	The reference sample			
controls	Control totals, by default initialized from the individual_controls and group_controls arguments			
field_names	Names of special fields, construct using special_field_names()			
individual_controls,group_controls				
	Control totals at individual and group level, given as a list of data frames where each data frame defines a control			
prior_weights	Prior (or design) weights at group level; by default a vector of ones will be used, which corresponds to random sampling of groups			

geo_hierarchyA table shows mapping between a larger zoning level to many zones of a smaller zoning level. The column name of the larger level should be specified in field_name as 'region' and the smaller one as 'zone'.xAn objectIgnored.groupId, individualId Name of the column that defines the ID of the group or the individualindividualsPerGroup Obsolete.countName of control total column in control tables (use first numeric column in each control by default).region, zoneName of the column that defines the region of the reference sample or the zone of the controls. Note that region is a larger area that contains more than one zone.		
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groupId, individualId Name of the column that defines the ID of the group or the individual individualsPerGroup Obsolete. count Name of control total column in control tables (use first numeric column in each control by default). region, zone Name of the column that defines the region of the reference sample or the zone of the controls. Note that region is a larger area that contains more than one	х	An object
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countName of control total column in control tables (use first numeric column in each control by default).region, zoneName of the column that defines the region of the reference sample or the zone of the controls. Note that region is a larger area that contains more than one	individualsPerG	iroup
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of the controls. Note that region is a larger area that contains more than one	count	
	region, zone	of the controls. Note that region is a larger area that contains more than one

Value

An object of class ml_problem or a list of them if geo_hierarchy was given, essentially a named list with the following components:

refSample The reference sample, a data.frame.

controls A named list with two components, individual and group. Each contains a list of controls as data.frames.

fieldNames A named list with the names of special fields.

is_ml_problem() returns a logical.

Examples

Create example from Ye et al., 2009

```
# Provide reference sample
ye <- tibble::tribble(</pre>
  ~HHNR, ~PNR, ~APER, ~HH_VAR, ~P_VAR,
  1, 1, 3, 1, 1,
 1, 2, 3, 1, 2,
  1, 3, 3, 1, 3,
  2, 4, 2, 1, 1,
  2, 5, 2, 1, 3,
  3, 6, 3, 1, 1,
  3, 7, 3, 1, 1,
  3, 8, 3, 1, 2,
  4, 9, 3, 2, 1,
  4, 10, 3, 2, 3,
  4, 11, 3, 2, 3,
  5, 12, 3, 2, 2,
  5, 13, 3, 2, 2,
  5, 14, 3, 2, 3,
  6, 15, 2, 2, 1,
```

ml_replicate

```
6, 16, 2, 2, 2,
  7, 17, 5, 2, 1,
  7, 18, 5, 2, 1,
  7, 19, 5, 2, 2,
  7, 20, 5, 2, 3,
  7, 21, 5, 2, 3,
  8, 22, 2, 2, 1,
  8, 23, 2, 2, 2
)
ye
# Specify control at household level
ye_hh <- tibble::tribble(</pre>
  ~HH_VAR, ~N,
           35,
  1,
           65
  2,
)
ye_hh
# Specify control at person level
ye_ind <- tibble::tribble(</pre>
  ~P_VAR, ~N,
  1, 91,
  2, 65,
  3, 104
)
ye_ind
ye_problem <- ml_problem(</pre>
  ref_sample = ye,
  field_names = special_field_names(
    groupId = "HHNR", individualId = "PNR", count = "N"
  ),
  group_controls = list(ye_hh),
  individual_controls = list(ye_ind)
)
ye_problem
fit <- ml_fit_dss(ye_problem)</pre>
fit$weights
```

ml_replicate

Replicate records in a reference sample based on its fitted weights

Description

This function replicates each entry in a reference sample based on its fitted weights. This is useful if the result of multiple replication algorithms are compared to each other, or to generate a full synthetic population based on the result of a ml_fit object. Note that, all individual and group ids of the synthetic population are not the same as those in the original reference sample, and the total number of groups replicated is always very close to or equal the sum of the fitted group weights.

Usage

```
ml_replicate(
   ml_fit,
   algorithm = c("pp", "trs", "round"),
   verbose = FALSE,
   .keep_original_ids = FALSE
)
```

Arguments

ml_fit	A ml_fit object created by the ml_fit() family.
algorithm	Replication algorithm to use. "trs" is the 'Truncate, replicate, sample' integeri- sation algorithm proposed by Lovelace et al. (2013), "pp" is weighted sampling with replacement, and "round" is just simple rounding.
verbose	If TRUE, print diagnostic output.
.keep_original	_ids
	If TRUE, the original individual and group ids of the reference sample will be kept with suffix '_old'.

Value

The function returns a replicated sample in data.frame in the format used in the reference sample of the input ml_fit object.

References

```
Lovelace, R., & Ballas, D. (2013). 'Truncate, replicate, sample':
   A method for creating integer weights for spatial microsimulation.
   Computers, Environment and Urban Systems, 41, 1-11.
```

Examples

```
path <- toy_example("Tiny")
fit <- ml_fit(ml_problem = readRDS(path), algorithm = "entropy_o")
syn_pop <- ml_replicate(fit, algorithm = "trs")
syn_pop</pre>
```

toy_example	Access to toy examples bundled in this p	package

Description

Returns the paths to all available toy examples, or to a specific toy example. Load via readRDS().

Usage

```
toy_example(name = NULL)
```

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toy_example

Arguments

name Name

Name of the example, default: return all

Value

A named vector of file system paths.

Examples

toy_example()

```
# Load example with results from Ye et al. (2009)
readRDS(toy_example("Tiny"))
```

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