# Package 'quadVAR'

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Version 0.1.2
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Author Jingmeng Cui [aut, cre] (ORCID: <a href="https://orcid.org/0000-0003-3421-8457">https://orcid.org/0000-0003-3421-8457</a> )
Maintainer Jingmeng Cui <jingmeng.cui@outlook.com></jingmeng.cui@outlook.com>
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block\_cv

Use Block Cross-Validation to Evaluate Models

## Description

This function uses block cross-validation to evaluate a model. The data is split into blocks, and the model is fit on all but one block and evaluated on the remaining block. This process is repeated for each block, and the mean squared error is calculated for each model.

## Usage

```
block_cv(
  data,
  dayvar = NULL,
  model,
  block = 10,
  lowerbound = -Inf,
  upperbound = Inf,
  detail = FALSE,
  metric = "MSE"
)
```

## Arguments

data	A data frame.
dayvar	A character string. The name of the variable that represents the day. This is required because this function use dayvar to specify the time point before the test block should not be used to predict the time point after the test block. If dayvar is not specified, in the original dataset, then please add one constant variable as dayvar, and specify it both here and in the function passed to model.
model	A function. The model to be evaluated. The function should take a data frame as its first argument and return a quadVAR object. It can be, for example, function(x) $quadVAR(x, vars = c("var1", "var2"))$
block	An integer. The number of blocks to use in the cross-validation. The default is 10.

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lowerbound	A numeric value or a vector with the same length as the number of variables that specifies the lower bound of the predicted values. If the predicted value is less than this value, it will be replaced by this value. The default value is -Inf.
upperbound	A numeric value or a vector with the same length as the number of variables that specifies the upper bound of the predicted values. If the predicted value is greater than this value, it will be replaced by this value. The default value is Inf.
detail	A logical. If TRUE, the function will return the predictions for each model. The default is FALSE, which only returns the mean squared error for each model.
metric	A character vector. The metric to be used to evaluate the model. The default is "MSE", which calculates the mean squared error. The other option is "MAE", which calculates the mean absolute error. Only effective when detail = FALSE.

## Value

Depending on detail. If FALSE, it returns a list of mean squared errors for each model. If TRUE, it returns a list with the mean squared errors for each model, the true data, and the predictions for each model.

compare_4_emo	Compare estimated model with true model for 4-emotion model

## Description

This function compares the estimated model with the true model for the 4-emotion model. It prints out the estimated coefficients and the true coefficients for the main effects and interaction effects.

## Usage

```
compare_4_emo(model, silent = FALSE)
```

## **Arguments**

model The estimated model, using data simulated from sim\_4\_emo(), and model esti-

mated using quadVAR().

silent Whether to print out the results.

#### Value

Silently return data frame with the estimated coefficients and the true coefficients for the main effects and interaction effects, while printing out the results rounded to two digits if silent = FALSE.

get\_adj\_mat

find_index	Find index of data that satisfies certain conditions
------------	--

## Description

Find index of data that satisfies certain conditions

#### Usage

```
find_index(data, dayvar, beepvar)
```

## **Arguments**

data A data frame.

dayvar String indicating assessment day. Adding this argument makes sure that the first

measurement of a day is not regressed on the last measurement of the previous day. IMPORTANT: only add this if the data has multiple observations per day.

beepvar Optional string indicating assessment beep per day. Adding this argument will

cause non-consecutive beeps to be treated as missing!

#### Value

A list of two vectors of indices.

get_adj_mat	Extract the adjacency matrix from a quadVAR object.
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## **Description**

Extract the adjacency matrix from a quadVAR object.

## Usage

```
get_adj_mat(model, value)
```

## **Arguments**

model A quadVAR object.

value The actual\_value in the output of linear\_quadVAR\_network().

## Value

An adjacency matrix.

linear\_quadVAR\_network

Linearize a quadVAR object to produce a network.

#### **Description**

A quadVAR object is nonlinear, which means that the relationship between variables are not the same across different values of the variables. This function linearizes a quadVAR object by specifying the values of the variables that the linearized model will be based on, to facilitate interpretation. The linearized model is then expressed in an adjacency matrix, which can be used to produce a network.

#### **Usage**

```
linear_quadVAR_network(model, value = NULL, value_standardized = TRUE)
## S3 method for class 'linear_quadVAR_network'
plot(x, interactive = FALSE, ...)
```

#### **Arguments**

model

A quadVAR object.

value

A numeric vector of length 1 or the same as the number of nodes, that specifies the values of the variables that the linearized model will be based on. If the length is 1, the same value will be used for all variables. The default value is NULL, in which case the value will be set to 0 in calculation, which means (if value\_standardized = TRUE) the linearized model will be based on the mean values of all variables.

value\_standardized

A logical value that specifies whether the input value is standardized or not. If TRUE, the input value will be regarded as standardized value, i.e., mean + value \* sd (e.g., 0 is the mean, 1 is mean + sd, ...). If FALSE, the input value will regarded as in the raw scale of the input data. If the raw dataset was already standardized, this parameter does not have an effect. The default value is TRUE.

Χ

A linear\_quadVAR\_network object.

interactive

Whether to produce an interactive plot using shiny (in which the user can change the values of variables interactively) or a static plot using qgraph::qgraph(). Default is FALSE.

. . .

Other arguments passed to qgraph::qgraph().

#### Value

A linear\_quadVAR\_network with the following elements:

- adj\_mat: the adjacency matrix of the linearized network.
- standardized\_value: the standardized value that the linearized model is based on.

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- actual\_value: the value in the raw scale of the input data.
- model: the input quadVAR object.
- value\_standardized: the same as the input.

#### Methods (by generic)

• plot(linear\_quadVAR\_network): Produce a plot for the linearized quadVAR model. If interactive = FALSE, the output will be a qgraph object, which can be further used to calculate centrality measures using, e.g., qgraph::centrality() and qgraph::centralityPlot().

#### References

The idea of this linearization function is inspired by Kroc, E., & Olvera Astivia, O. L. (2023). The case for the curve: Parametric regression with second- and third-order polynomial functions of predictors should be routine. Psychological Methods. https://doi.org/10.1037/met0000629

partial_plot	Make a partial plot of a variable in a model This function takes a quadVAR model as input, and returns a plot of the partial effect of a variable on the dependent variable (controlling all other variables and
	the intercept), for higher and lower levels of the moderator variable split by the median.

## Description

Make a partial plot of a variable in a model This function takes a quadVAR model as input, and returns a plot of the partial effect of a variable on the dependent variable (controlling all other variables and the intercept), for higher and lower levels of the moderator variable split by the median.

## Usage

```
partial_plot(model, y, x, moderator)
```

#### **Arguments**

model	A quadVAR model
У	The dependent variable
x	The variable for which the partial effect is plotted
moderator	The moderator variable

#### Value

A ggplot object

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predict.quadVAR	Predict the value	s of the dependent	variables using the quadVAR
	model		

## **Description**

Predict the values of the dependent variables using the quadVAR model

#### Usage

```
## S3 method for class 'quadVAR'
predict(
  object,
  newdata = NULL,
  donotpredict = NULL,
  lowerbound = -Inf,
  upperbound = Inf,
  with_const = FALSE,
  ...
)
```

#### **Arguments**

object A quadVAR object.

newdata A data frame or tibble containing at least the values of the independent variables,

dayvar, and beepvar (if used in model estimation). If NULL, the original data

used to fit the model will be used.

donotpredict NOT IMPLEMENTED YET! A character vector of the model names that are

not used for prediction. Possible options include "AR", "VAR", "VAR\_full", "quadVAR\_full", "all\_others", with NULL as the default. If set "all\_others", then only a quadVAR model will be estimated. For datasets with large number of

variables, you may set this parameter to "quadVAR\_full" to save time.

lowerbound A numeric value or a vector with the same length as the number of variables that

specifies the lower bound of the predicted values. If the predicted value is less than this value, it will be replaced by this value. The default value is -Inf.

upperbound A numeric value or a vector with the same length as the number of variables

that specifies the upper bound of the predicted values. If the predicted value is greater than this value, it will be replaced by this value. The default value is Inf.

with\_const A logical value indicating whether to include the constant variables in the pre-

diction. Those variables were automatically excluded in the estimation procedure. The default value is FALSE. When set to TRUE, the lowerbound and upperbound should be a vector with the same length as the number of variables in the model, including the constant variables. The values of the constant variables will be ignored though because their predicted values are always the same,

which is the constant value in the input data.

... Other arguments passed to the RAMP::predict.RAMP() function.

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#### Value

A data frame or tibble containing the predicted values of the dependent variables. If a value cannot be predicted (e.g., because the corresponding previous time point is not in the data), it will be NA.

quadVAR

Estimate lag-1 quadratic vector autoregression models

#### **Description**

This function estimate regularized nonlinear quadratic vector autoregression models with strong hierarchy using the RAMP::RAMP() algorithm, and also compare it with the linear AR, regularized VAR, and unregularized (full) VAR and quadratic VAR models.

## Usage

```
quadVAR(
  data,
  vars,
  dayvar = NULL,
  beepvar = NULL,
  penalty = "LASSO",
  tune = "EBIC",
  donotestimate = NULL,
  SIS_options = list(),
  RAMP_options = list()
)
## S3 method for class 'quadVAR'
print(x, ...)
## S3 method for class 'quadVAR'
summary(object, ...)
## S3 method for class 'quadVAR'
coef(object, ...)
## S3 method for class 'coef_quadVAR'
print(
  х,
  use_actual_names = TRUE,
  abbr = FALSE,
 minlength = 3,
  omit_zero = TRUE,
  digits = 2,
  row.names = FALSE,
```

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```
)
    ## S3 method for class 'quadVAR'
    plot(x, value = NULL, value\_standardized = TRUE, interactive = FALSE, ...)
Arguments
    data
                      A tibble, data.frame, or matrix that represents a time series of vectors, with
                      each row as a time step.
                      A character vector of the variable names used in the model.
    vars
    dayvar
                      String indicating assessment day. Adding this argument makes sure that the first
                      measurement of a day is not regressed on the last measurement of the previous
                      day. IMPORTANT: only add this if the data has multiple observations per day.
                      Optional string indicating assessment beep per day. Adding this argument will
    beepvar
                      cause non-consecutive beeps to be treated as missing!
                      The penalty used for the linear and regularized VAR models. Possible options
    penalty
                      include "LASSO", "SCAD", "MCP", with "LASSO" as the default.
                      Tuning parameter selection method. Possible options include "AIC", "BIC",
    tune
                      "EBIC", with "EBIC" as the default.
    donotestimate
                      A character vector of the model names that are not estimated. Possible op-
                      tions include, "NULL_model", "AR", "VAR", "VAR_full", "quadVAR_full",
                      "all_others", with NULL as the default. If set "all_others", then only a quadVAR
                      model will be estimated. For datasets with large number of variables, you may
                      set this parameter to "quadVAR_full" to save time.
    SIS_options
                      A list of other parameters for the SIS::tune.fit() function. This is used for
                      the regularized VAR models.
                      A list of other parameters for the RAMP::RAMP() function. This is used for the
    RAMP_options
                      nonlinear quadratic VAR model.
                      For print.guadVAR, additional arguments passed to print.coef_guadVAR().
    . . .
                      For print.coef_quadVAR, additional arguments passed to print.data.frame().
                      An quadVAR object. (For print.coef_quadVAR, an coef_quadVAR object re-
    object, x
                      turned by coef.quadVAR().)
    use_actual_names
                      Logical. If TRUE, the actual variable names are used in the output. If FALSE, the
                      names "X1", "X2", etc., are used in the output. Default is TRUE.
    abbr
                      Logical. If TRUE, the output is abbreviated. Default is FALSE.
    minlength
                      the minimum length of the abbreviations.
    omit_zero
                      Logical. If TRUE, the coefficients that are zero are omitted. Default is FALSE.
                      the minimum number of significant digits to be used: see print.default.
    digits
    row.names
                      logical (or character vector), indicating whether (or what) row names should be
```

A numeric vector of length 1 or the same as the number of nodes, that specifies the values of the variables that the linearized model will be based on. If the length is 1, the same value will be used for all variables. The default value is

printed.

value

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NULL, in which case the value will be set to 0 in calculation, which means (if value\_standardized = TRUE) the linearized model will be based on the mean values of all variables.

## value\_standardized

A logical value that specifies whether the input value is standardized or not. If TRUE, the input value will be regarded as standardized value, i.e., mean + value \* sd (e.g., 0 is the mean, 1 is mean + sd, ...). If FALSE, the input value will regarded as in the raw scale of the input data. If the raw dataset was already standardized, this parameter does not have an effect. The default value is TRUE.

interactive

Whether to produce an interactive plot using shiny (in which the user can change the values of variables interactively) or a static plot using qgraph::qgraph(). Default is FALSE.

#### Value

An quadVAR object that contains the following elements:

- NULL\_model: A list of NULL models for each variable.
- AR\_model: A list of linear AR models for each variable.
- VAR\_model: A list of regularized VAR models for each variable.
- VAR\_full\_model: A list of unregularized (full) VAR models for each variable.
- quadVAR\_model: A list of regularized nonlinear quadratic VAR models for each variable.
- quadVAR\_full\_model: A list of unregularized (full) nonlinear quadratic VAR models for each variable.
- data,vars,penalty,tune,SIS\_options,RAMP\_options: The input arguments.
- data\_x,data\_y: The data directly used for modeling.

## Methods (by generic)

- print(quadVAR): Print the coefficients for a quadVAR object. See coef.quadVAR() and print.coef\_quadVAR() for details.
- summary(quadVAR): Summary of a quadVAR object. Different IC definitions used by different packages (which differ by a constant) are unified to make them comparable to each other.
- coef(quadVAR): Extract the coefficients from a quadVAR object.
- plot(quadVAR): Produce a plot for the linearized quadVAR model. Equivalent to first produce a linear quadVAR network using linear\_quadVAR\_network(), then use plot.linear\_quadVAR\_network().

#### **Functions**

• print(coef\_quadVAR): Print the coefficients from a quadVAR object.

#### See Also

linear\_quadVAR\_network()

quadVAR\_to\_dyn\_eqns

#### **Examples**

```
set.seed(1614)
data <- sim_4_emo(time = 200, sd = 1)
plot(data[, "x1"])
qV1 <- quadVAR(data, vars = c("x1", "x2", "x3", "x4"))
summary(qV1)
coef(qV1)
plot(qV1)
# Compare the estimation with the true model
plot(true_model_4_emo())
plot(qV1, value = 0, value_standardized = FALSE, layout = plot(true_model_4_emo())$layout)</pre>
```

quadVAR\_to\_dyn\_eqns

Transform a quadVAR object to a list of dynamic equations.

## **Description**

Transform a quadVAR object to a list of dynamic equations.

## Usage

```
quadVAR_to_dyn_eqns(model, minus_self = TRUE)
```

## **Arguments**

model A quadVAR object.

minus\_self Whether to subtract the term itself from the equation. If TRUE, the equation will

be in the form of  $(0 =) \dots$  - X1; if FALSE, the equation will be in the form of

 $(X1 = ) \dots$ 

## Value

A list of dynamic equations in characters. You can also use rlang::parse\_expr() to parse them into expressions.

sim\_4\_emo

Simulate a 4-emotion model

## Description

This function simulates a 4-emotion model which is nonlinear, bistable, discrete, and (almost) centered to zero. Adapted from the model described by van de Leemput et al. (2014).

## Usage

```
sim_4_emo(time = 200, init = c(1.36, 1.36, 4.89, 4.89), sd = 1)
```

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## **Arguments**

time	The number of time steps to simulate.
init	A vector of initial values for the four variables. Default is $c(1.36, 1.36, 4.89, 4.89)$ , which is one of the stable states of the model.
sd	The standard deviation of the noise.

#### Value

A matrix with the simulated data.

## References

van de Leemput, I. A., Wichers, M., Cramer, A. O., Borsboom, D., Tuerlinckx, F., Kuppens, P., ... & Scheffer, M. (2014). Critical slowing down as early warning for the onset and termination of depression. Proceedings of the National Academy of Sciences, 111(1), 87-92.

#### See Also

```
true_model_4_emo(), compare_4_emo(), quadVAR()
```

## Description

This function generate the true model for the 4-emotion model. It can used to compare the estimated model with the true model, or to plot the true model.

#### Usage

```
true_model_4_emo(...)
## S3 method for class 'true_model_4_emo'
coef(object, ...)
## S3 method for class 'true_model_4_emo'
print(x, which = NULL, ...)
```

## **Arguments**

	Not in use.
object	A true_model_4_emo object.
X	A true_model_4_emo object.
which	Which model to print out. There are four models in total, corresponding to the four variables.

#### Value

```
A true_model_4_emo object.

NULL, but prints out the true model.
```

## Methods (by generic)

- coef(true\_model\_4\_emo): This function returns the coefficients for the 4-emotion model. It is also used in other functions to generate the linearized version of the true model and to make plots. It returns a list of coefficients for the 4-emotion model, in the same format as coef.quadVAR()
- print(true\_model\_4\_emo): This function prints out the true model for the 4-emotion model in the same format as RAMP::RAMP(), to help users to compare the true model and the estimated model.

#### See Also

```
true_model_4_emo(), compare_4_emo(), quadVAR()
```

## **Examples**

```
coef(true_model_4_emo())
plot(true_model_4_emo())

if (interactive()) {
    # This code will only run in an interactive session
    plot(true_model_4_emo(), interactive = TRUE)
}
```

tune.fit

Using the **glmnet** and **ncvreg** packages, fits a Generalized Linear Model or Cox Proportional Hazards Model using various methods for choosing the regularization parameter  $\lambda$ 

## Description

This function is modified from SIS::tune.fit(). It is used to tune the regularization parameter for the regularized VAR models. This wrapper is used because of the following reasons.

- 1. The original SIS::tune.fit() function does not return the value of the information criteria that we would like to use.
- 2. We use the nevreg package exclusively (so we removed the code using the glmnet package). This is to make the result more consistent, and also because the nevreg package has better support for the calculation of information criteria.
- 3. We also removed the generalized linear model (GLM) option, and the cross-validation option because we do not use them.
- 4. We use stats::AIC() and stats::BIC() instead of the ones using SIS:::loglik() to make the calculation methods more consistent.
- 5. We added . . . to allow the user to pass additional arguments to the nevreg::nevreg() function.

#### Usage

```
tune.fit(
  Х,
  у,
  family = "gaussian",
  penalty = c("SCAD", "MCP", "lasso"),
  concavity.parameter = switch(penalty, SCAD = 3.7, 3),
  tune = c("aic", "bic", "ebic"),
  type.measure = c("deviance", "class", "auc", "mse", "mae"),
  gamma.ebic = 1,
)
```

#### **Arguments**

The design matrix, of dimensions n \* p, without an intercept. Each row is an Х observation vector.

The response vector of dimension n \* 1. Quantitative for family='gaussian', У non-negative counts for family='poisson', binary (0-1) for family='binomial'. For family='cox', y should be an object of class Surv, as provided by the func-

tion Surv() in the package survival.

family Response type (see above).

The penalty to be applied in the regularized likelihood subproblems. 'SCAD' penalty (the default), 'MCP', or 'lasso' are provided.

concavity.parameter

The tuning parameter used to adjust the concavity of the SCAD/MCP penalty. Default is 3.7 for SCAD and 3 for MCP.

Method for selecting the regularization parameter along the solution path of the penalized likelihood problem. Options to provide a final model include tune='cv', tune='aic', tune='bic', and tune='ebic'. See references at

the end for details.

Loss to use for cross-validation. Currently five options, not all available for all models. The default is type.measure='deviance', which uses squared-error for gaussian models (also equivalent to type.measure='mse' in this case), deviance for logistic and poisson regression, and partial-likelihood for the Cox model. Both type.measure='class' and type.measure='auc' apply only to logistic regression and give misclassification error and area under the ROC curve, respectively. type.measure='mse' or type.measure='mae' (mean absolute error) can be used by all models except the 'cox'; they measure the deviation from the fitted mean to the response. For penalty='SCAD' and penalty='MCP',

only type.measure='deviance' is available.

Specifies the parameter in the Extended BIC criterion penalizing the size of the corresponding model space. The default is gamma.ebic=1. See references at the end for details.

additional arguments to be passed to the nevreg::nevreg() function.

tune

type.measure

gamma.ebic

#### **Details**

Original description from SIS::tune.fit():

This function fits a generalized linear model or a Cox proportional hazards model via penalized maximum likelihood, with available penalties as indicated in the **glmnet** and **nevreg** packages. Instead of providing the whole regularization solution path, the function returns the solution at a unique value of  $\lambda$ , the one optimizing the criterion specified in tune.

#### Value

#### Returns an object with

ix	The vector of indices of the nonze	ero coefficients selected by the maxim	num pe-

nalized likelihood procedure with tune as the method for choosing the regular-

ization parameter.

a0 The intercept of the final model selected by tune.

beta The vector of coefficients of the final model selected by tune.

fit The fitted penalized regression object.

lambda The corresponding lambda in the final model.

lambda.ind The index on the solution path for the final model.

#### Author(s)

Jianqing Fan, Yang Feng, Diego Franco Saldana, Richard Samworth, and Yichao Wu

#### References

Jerome Friedman and Trevor Hastie and Rob Tibshirani (2010) Regularization Paths for Generalized Linear Models Via Coordinate Descent. *Journal of Statistical Software*, **33**(1), 1-22.

Noah Simon and Jerome Friedman and Trevor Hastie and Rob Tibshirani (2011) Regularization Paths for Cox's Proportional Hazards Model Via Coordinate Descent. *Journal of Statistical Software*, **39**(5), 1-13.

Patrick Breheny and Jian Huang (2011) Coordinate Descent Algorithms for Nonconvex Penalized Regression, with Applications to Biological Feature Selection. *The Annals of Applied Statistics*, **5**, 232-253.

Hirotogu Akaike (1973) Information Theory and an Extension of the Maximum Likelihood Principle. In *Proceedings of the 2nd International Symposium on Information Theory*, BN Petrov and F Csaki (eds.), 267-281.

Gideon Schwarz (1978) Estimating the Dimension of a Model. The Annals of Statistics, 6, 461-464.

Jiahua Chen and Zehua Chen (2008) Extended Bayesian Information Criteria for Model Selection with Large Model Spaces. *Biometrika*, **95**, 759-771.

## Examples

```
set.seed(0)
data("leukemia.train", package = "SIS")
y.train <- leukemia.train[, dim(leukemia.train)[2]]
x.train <- as.matrix(leukemia.train[, -dim(leukemia.train)[2]])
x.train <- SIS::standardize(x.train)
model <- tune.fit(x.train[, 1:3500], y.train, family = "binomial", tune = "bic")
model$ix
model$a0
model$beta</pre>
```

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