

# Package ‘robmed’

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**Type** Package

**Title** (Robust) Mediation Analysis

**Version** 1.2.1

**Date** 2025-02-08

**Depends** R (>= 3.5.0), ggplot2 (>= 3.3.0), robustbase (>= 0.92-7)

**Imports** boot (>= 1.3-20), grid, methods, quantreg (>= 5.36), sn (>= 1.5-4), utils

**Suggests** knitr, testthat

**Description** Perform mediation analysis via the fast-and-robust bootstrap test ROBMed (Alfons, Ates & Groenen, 2022a; <[doi:10.1177/1094428121999096](https://doi.org/10.1177/1094428121999096)>), as well as various other methods. Details on the implementation and code examples can be found in Alfons, Ates, and Groenen (2022b) <[doi:10.18637/jss.v103.i13](https://doi.org/10.18637/jss.v103.i13)>. Further discussion on robust mediation analysis can be found in Alfons & Schley (2024) <[doi:10.31234/osf.io/2hqdy](https://doi.org/10.31234/osf.io/2hqdy)>.

**License** GPL (>= 2)

**URL** <https://github.com/aalfons/robmed>

**BugReports** <https://github.com/aalfons/robmed/issues>

**LazyData** yes

**VignetteBuilder** knitr

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provided the BSG2014 data)

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robmed-package	<i>(Robust) Mediation Analysis</i>
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Description

Perform mediation analysis via the fast-and-robust bootstrap test ROBMed (Alfons, Ates & Groenen, 2022a; <doi:10.1177/1094428121999096>), as well as various other methods. Details on the implementation and code examples can be found in Alfons, Ates, and Groenen (2022b) <doi:10.18637/jss.v103.i13>. Further discussion on robust mediation analysis can be found in Alfons & Schley (2024) <doi:10.31234/osf.io/2hqdy>.

Details

The DESCRIPTION file:

Package: robmed  
Type: Package  
Title: (Robust) Mediation Analysis

```

Version:      1.2.1
Date:         2025-02-08
Depends:      R (>= 3.5.0), ggplot2 (>= 3.3.0), robustbase (>= 0.92-7)
Imports:      boot (>= 1.3-20), grid, methods, quantreg (>= 5.36), sn (>= 1.5-4), utils
Suggests:     knitr, testthat
Description:   Perform mediation analysis via the fast-and-robust bootstrap test ROBMed (Alfons, Ates & Groenen, 202
License:      GPL (>= 2)
URL:          https://github.com/aalfons/robmed
BugReports:   https://github.com/aalfons/robmed/issues
LazyData:     yes
VignetteBuilder: knitr
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Maintainer:   Andreas Alfons <alfons@ese.eur.nl>
Encoding:     UTF-8
RoxygenNote:  7.3.2

```

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confint.test_mediation	Confidence intervals from (robust) mediation analysis
cov_Huber	Huber M-estimator of location and scatter
cov_ML	Maximum likelihood estimator of mean vector and covariance matrix
cov_control	Tuning parameters for Huber M-estimation of location and scatter
density_plot	Density plot of the indirect effect(s)
ellipse_plot	Diagnostic plot with a tolerance ellipse
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m	Create an object of hypothesized mediators or control variables
p_value	p-Values from (robust) mediation analysis
plot-methods	Plot (robust) mediation analysis results
reg_control	Tuning parameters for robust regression
retest	Retest for mediation
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test_mediation	(Robust) mediation analysis
weight_plot	Diagnostic plot of robust regression weights
weights.cov_Huber	Robustness weights of Huber M-estimation of location and scatter

### Author(s)

Andreas Alfons [aut, cre] (<<https://orcid.org/0000-0002-2513-3788>>), Nufer Y. Ates [ctb] (<<https://orcid.org/0000-0003-4572-4101>>, provided the BSG2014 data)

Maintainer: Andreas Alfons <[alfons@ese.eur.nl](mailto:alfons@ese.eur.nl)>

### References

Alfons, A., Ates, N.Y. and Groenen, P.J.F. (2022a) A Robust Bootstrap Test for Mediation Analysis. *Organizational Research Methods*, **25**(3), 591–617. doi:10.1177/1094428121999096.

Alfons, A., Ates, N.Y. and Groenen, P.J.F. (2022b) Robust mediation analysis: The R package **robmed**. *Journal of Statistical Software*, **103**(13), 1–45. doi:10.18637/jss.v103.i13.

### See Also

Useful links:

- <https://github.com/aalfons/robmed>
- Report bugs at <https://github.com/aalfons/robmed/issues>

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boot_samples	<i>Draw bootstrap samples</i>
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### Description

Draw bootstrap samples to be used for (fast-and-robust) bootstrap tests for mediation analysis. Note that this function is intended for use in simulation studies by experienced users.

### Usage

```
boot_samples(n, R)
```

### Arguments

n	an integer giving the number of observations in the original data set.
R	an integer giving the number of bootstrap samples to be generated.

**Value**

An object of class "boot\_samples" with the following components:

indices	an integer matrix in which each column contains the indices of the corresponding bootstrap sample.
seed	the state of the random number generator before the bootstrap samples were drawn

**Author(s)**

Andreas Alfons

## See Also

```
test_mediation()
```

## Examples

```
# control parameters  
n <- 100  
a <- b <- c <- 0.4  
  
# generate data  
set.seed(20200309)  
x <- rnorm(n)  
m <- a * x + rnorm(n)  
y <- b * m + c * x + rnorm(n)  
simulated_data <- data.frame(x, y, m)  
  
# perform bootstrap tests  
indices <- boot_samples(n, R = 5000)  
robust_boot <- test_mediation(simulated_data,  
                             x = "x", y = "y", m = "m",  
                             robust = TRUE,  
                             indices = indices)  
  
summary(robust_boot)  
  
ols_boot <- test_mediation(simulated_data,  
                          x = "x", y = "y", m = "m",  
                          robust = FALSE,  
                          indices = indices)  
  
summary(ols_boot)
```

**Description**

The data were collected from 354 senior business administration students during a business simulation game at a Western European University.

The game was played for a total of 12 rounds (i.e., two separate games of 6 rounds) as part of the capstone strategy class. Students were randomly assigned to teams of four, and surveyed in three waves: prior to the first game, in between the two games, and after the second game (with different variables being surveyed in the different waves).

The 354 students formed 92 teams, and the responses of individual students were aggregated to the team level. Leaving out teams with less than 50 percent response rate yields  $n = 89$  teams. Only a small subset of the collected variables are included here.

**Usage**

```
data("BSG2014")
```

**Format**

A data frame with 89 observations on the following 13 variables.

**ProcessConflict** Based on Shah & Jehn (1993), the team members rated three items on the presence of conflict related to the process of working together, using a 5-point scale (1 = none, 5 = a lot). The individual responses were aggregated by taking the average across items and team members. Process conflict was measured in the second survey (between the two games).

**SharedExperience** As teams were randomly formed, no prior shared group experience is expected, and shared group experience and training is developed during the first game for the second game. Hence the team performance score on the first game is used as a proxy for the level of shared group experience and training. Those scores were computed through a mix of five objective performance measures: return on equity, earnings-per-share, stock price, credit rating, and image rating. The computation of the scores is handled by the simulation game software, and details can be found in Mathieu & Rapp (2009). The scores ranged from 57 to 111, and they were communicated to the teams only after the third survey.

**TaskConflict** Using the intra-group conflict scale of Jehn (1995), the team members rated four items on the presence of conflict regarding the work on a 5-point scale (1 = none, 5 = a lot). The individual responses were aggregated by taking the average across items and team members. Task conflict was measured in the second survey (between the two games).

**TeamCommitment** The team members indicated the extent to which they agree or disagree with four items on commitment to the team, which are based on Mowday, Steers & Porter (1979), using a 5-point scale (1 = strongly disagree, 5 = strongly agree). The individual responses were aggregated by taking the average across items and team members. Team commitment was measured in the third survey (after the second game).

- TeamPerformance** Following Hackman (1986), the team members indicated the extent to which they agree or disagree with four items on the team's functioning, using a 5-point scale (1 = strongly disagree, 5 = strongly agree). The individual responses were aggregated by taking the average across items and team members. Subjective team performance was measured in the third survey (after the second game).
- TMS** Transactive memory systems (TMS) are defined as shared systems that people in relationships develop for encoding, storing, and retrieving information about different substantive domains. TMS was operationalized with Lewis' (2003) 15-item scale that measures the three sub-dimensions of TMS (specialization, credibility, and coordination). For each item, the team members responded on a 5-point scale (1 = strongly disagree, 5 = strongly agree). Following Lewis (2003), the three sub dimensions were aggregated to form the TMS construct. That is, the individual responses were aggregated by taking the average across all 15 items and team members. TMS was measured in the second survey (between the two games).
- ValueDiversity** Using the short Schwartz's value survey (Lindeman & Verkasalo, 2005), the team members rated ten items on the importance of certain values (1 = not important, 10 = highly important). For each value item, the coefficient of variation of the individual responses across team members was computed, and the resulting coefficients of variation were averaged across the value items. Value diversity was measured in the first survey (before the first game).
- ProceduralJustice** Based on the intra-unit procedural justice climate scale of Li & Cropanzano (2009), the team members indicated the extent to which they agree or disagree with four items on a 5-point scale (1 = strongly disagree, 5 = strongly agree). The individual responses were aggregated by taking the average across items and team members. Procedural justice was measured in the third survey (after the second game).
- InteractionalJustice** Using the intra-unit interactional justice climate scale of Li & Cropanzano (2009), the team members indicated the extent to which they agree or disagree with four items on a 5-point scale (1 = strongly disagree, 5 = strongly agree). The individual responses were aggregated by taking the average across items and team members. Interactional justice was measured in the third survey (after the second game).
- SharedLeadership** Following Carson, Tesluk & Marrone (2007), every team member assessed each of their peers on the question of 'To what degree does your team rely on this individual for leadership?' using a 5-point scale (1 = not at all, 5 = to a very large extent). The leadership ratings were aggregated by taking the sum and dividing it by the number of pairwise relationships among team members. Shared leadership was measured in the second survey (between the two games).
- AgeDiversity** Following Harrison & Klein (2007), age diversity was operationalized by the coefficient of variation of the team members' ages.
- GenderDiversity** Gender diversity was measured with Blau's index,  $1 - \sum_j p_j^2$ , where  $p_j$  is the proportion of team members in the  $j$ -th category (Blau, 1977).
- TeamScore** The team performance scores on the second game were computed at the end of the simulation through a mix of five objective performance measures: return on equity, earnings-per-share, stock price, credit rating, and image rating. The computation of the scores is handled by the simulation game software, and details can be found in Mathieu & Rapp (2009). The scores ranged from 49 to 110, and they were communicated to the teams only after the third survey.

## Source

The data were collected and provided by Nufer Y. Ates (<https://orcid.org/0000-0003-4572-4101>).

## References

- Alfons, A., Ates, N.Y. and Groenen, P.J.F. (2022a) A Robust Bootstrap Test for Mediation Analysis. *Organizational Research Methods*, **25**(3), 591–617. doi:10.1177/1094428121999096.
- Alfons, A., Ates, N.Y. and Groenen, P.J.F. (2022b) Robust Mediation Analysis: The R Package **robmed**. *Journal of Statistical Software*, **103**(13), 1–45. doi:10.18637/jss.v103.i13.
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- Shah, P.P. and Jehn, K.A. (1993) Do Friends Perform Better than Acquaintances? The Interaction of Friendship, Conflict, and Task. *Group Decision and Negotiation*, **2**(2), 149–165. doi:10.1007/bf01884769.

## Examples

```
data("BSG2014")
summary(BSG2014)

# scatterplot matrix for the variables included in the
# illustrative mediation analysis of Alfons et al. (2022a)
x <- "ValueDiversity"
y <- "TeamCommitment"
```



```
m <- "TaskConflict"
plot(BSG2014[, c(x, y, m)], pch = 21, bg = "black")
```

---

ci\_plot

*Dot plot with confidence intervals*


---

## Description

Produce a dot plot with confidence intervals of selected effects from (robust) mediation analysis. In addition to confidence intervals, p-values of the selected effects can be plotted as well.

## Usage

```
ci_plot(object, ...)

## Default S3 method:
ci_plot(object, parm = c("direct", "indirect"), ...)

## S3 method for class 'boot_test_mediation'
ci_plot(
  object,
  parm = c("direct", "indirect"),
  type = c("boot", "data"),
  p_value = FALSE,
  digits = 4L,
  ...
)

## S3 method for class 'sobel_test_mediation'
ci_plot(
  object,
  parm = c("direct", "indirect"),
  level = 0.95,
  p_value = FALSE,
  ...
)

## S3 method for class 'list'
ci_plot(
  object,
  parm = c("direct", "indirect"),
  type = c("boot", "data"),
  level = 0.95,
  p_value = FALSE,
  digits = 4L,
  ...
)
```

```
## S3 method for class 'setup_ci_plot'
ci_plot(object, ...)
```

### Arguments

object	an object inheriting from class " <a href="#">test_mediation</a> " containing results from (robust) mediation analysis, or a list of such objects.
...	additional arguments to be passed down.
parm	an integer, character or logical vector specifying which effects to include in the plot. In case of a character vector, possible values are "a", "b", "d" (only serial multiple mediator models), "total", "direct", and "indirect". The default is to include the direct and the indirect effect(s).
type	a character string specifying which point estimates and confidence intervals to plot: those based on the bootstrap distribution ("boot"; the default), or those based on the original data ("data"). If "boot", the confidence intervals of effects other than the indirect effect(s) are computed using a normal approximation (i.e., assuming a normal distribution of the corresponding effect with the standard deviation computed from the bootstrap replicates). If "data", the confidence intervals of effects other than the indirect effect(s) are computed via statistical theory based on the original data (e.g., based on a t-distribution if the coefficients are estimated via regression). Note that this is only relevant for mediation analysis via a bootstrap test, where the confidence interval of the indirect effect is always computed via a percentile-based method due to the asymmetry of its distribution.
p_value	a logical indicating whether to include dot plots of the p-values in addition to those with confidence intervals. The default is FALSE.
digits	an integer determining how many digits to compute for bootstrap p-values of the indirect effects (see <a href="#">p_value()</a> ). The default is to compute 4 digits after the comma. This is only relevant if p_value = TRUE.
level	numeric; the confidence level of the confidence intervals from Sobel's test. The default is to include 95% confidence intervals. Note that this is not used for bootstrap tests, as those require to specify the confidence level already in <a href="#">test_mediation()</a> .

### Details

Methods first call [setup\\_ci\\_plot\(\)](#) to extract all necessary information to produce the plot, then the "setup\_ci\_plot" method is called to produce the plot.

### Value

An object of class "[ggplot](#)".

### Author(s)

Andreas Alfons

## References

Alfons, A., Ates, N.Y. and Groenen, P.J.F. (2022) Robust Mediation Analysis: The R Package **robmed**. *Journal of Statistical Software*, **103**(13), 1–45. doi:10.18637/jss.v103.i13.

## See Also

`test_mediation()`, `setup_ci_plot()`  
`density_plot()`, `ellipse_plot()`, `weight_plot()`, `plot()`

## Examples

```
data("BSG2014")

# run fast-and-robust bootstrap test
robust_boot <- test_mediation(BSG2014,
                             x = "ValueDiversity",
                             y = "TeamCommitment",
                             m = "TaskConflict",
                             level = 0.9,
                             robust = TRUE)

# create plot for robust bootstrap test
ci_plot(robust_boot)
ci_plot(robust_boot, color = "#00BFC4")

# run OLS bootstrap test
ols_boot <- test_mediation(BSG2014,
                           x = "ValueDiversity",
                           y = "TeamCommitment",
                           m = "TaskConflict",
                           level = 0.9,
                           robust = FALSE)

# compare robust and OLS bootstrap tests
boot_list <- list("OLS bootstrap" = ols_boot,
                 "ROBMED" = robust_boot)
ci_plot(boot_list)

# the plot can be customized in the usual way
ci_plot(boot_list) +
  geom_hline(yintercept = 0, color = "darkgrey") +
  coord_flip() + theme_bw() +
  labs(title = "OLS bootstrap vs ROBMED")
```

**Description**

Extract coefficients from models computed in (robust) mediation analysis.

**Usage**

```
## S3 method for class 'test_mediation'
coef(object, parm = NULL, ...)

## S3 method for class 'boot_test_mediation'
coef(object, parm = NULL, type = c("boot", "data"), ...)

## S3 method for class 'fit_mediation'
coef(object, parm = NULL, ...)
```

**Arguments**

object	an object inheriting from class " <a href="#">test_mediation</a> " containing results from (robust) mediation analysis, or an object inheriting from class " <a href="#">fit_mediation</a> " containing a (robust) mediation model fit.
parm	an integer, character or logical vector specifying the paths for which to extract coefficients, or NULL to extract all coefficients. In case of a character vector, possible values are "a", "b", "d" (only serial multiple mediator models), "total", "direct", and "indirect".
...	additional arguments are currently ignored.
type	a character string specifying whether to extract the means of the bootstrap distribution ("boot"; the default), or the coefficient estimates based on the original data set ("data").

**Value**

A numeric vector containing the requested coefficients.

**Author(s)**

Andreas Alfons

**See Also**

[test\\_mediation\(\)](#), [fit\\_mediation\(\)](#), [confint\(\)](#), [p\\_value\(\)](#)

**Examples**

```
data("BSG2014")

# fit robust mediation model and extract coefficients
fit <- fit_mediation(BSG2014,
  x = "ValueDiversity",
  y = "TeamCommitment",
  m = "TaskConflict")
```

```

coef(fit)

# run fast-and-robust bootstrap test and extract coefficients
boot <- test_mediation(fit, level = 0.9)
coef(boot, type = "data") # from original sample
coef(boot, type = "boot") # means of bootstrap replicates

```

---

confint.test\_mediation

*Confidence intervals from (robust) mediation analysis*

---

## Description

Extract or compute confidence intervals for effects in (robust) mediation analysis.

## Usage

```

## S3 method for class 'boot_test_mediation'
confint(object, parm = NULL, level = NULL, type = c("boot", "data"), ...)

## S3 method for class 'sobel_test_mediation'
confint(object, parm = NULL, level = 0.95, ...)

```

## Arguments

object	an object inheriting from class " <code>test_mediation</code> " containing results from (robust) mediation analysis.
parm	an integer, character or logical vector specifying the paths for which to extract or compute confidence intervals, or NULL to extract or compute confidence intervals for all coefficients. In case of a character vector, possible values are "a", "b", "d" (only serial multiple mediator models), "total", "direct", and "indirect".
level	for the "boot_test_mediation" method, this is ignored and the confidence level of the bootstrap confidence interval for the indirect effect is used. For the other methods, the confidence level of the confidence intervals to be computed. The default is to compute 95% confidence intervals.
type	a character string specifying how to compute the confidence interval of the effects other than the indirect effect(s). Possible values are "boot" (the default) to compute bootstrap confidence intervals using the normal approximation (i.e., to assume a normal distribution of the corresponding effect with the standard deviation computed from the bootstrap replicates), or "data" to compute confidence intervals via statistical theory based on the original data (e.g., based on a t-distribution if the coefficients are estimated via regression). Note that this is only relevant for mediation analysis via a bootstrap test, where the confidence interval of the indirect effect is always computed via a percentile-based method due to the asymmetry of its distribution.
...	additional arguments are currently ignored.

**Value**

A numeric matrix containing the requested confidence intervals.

**Author(s)**

Andreas Alfons

**See Also**

[test\\_mediation\(\)](#), [coef\(\)](#), [p\\_value\(\)](#), [boot.ci\(\)](#)

**Examples**

```
data("BSG2014")

# run fast-and-robust bootstrap test
robust_boot <- test_mediation(BSG2014,
                             x = "ValueDiversity",
                             y = "TeamCommitment",
                             m = "TaskConflict",
                             level = 0.9,
                             robust = TRUE)
confint(robust_boot, type = "boot")

# run OLS bootstrap test
ols_boot <- test_mediation(BSG2014,
                          x = "ValueDiversity",
                          y = "TeamCommitment",
                          m = "TaskConflict",
                          level = 0.9,
                          robust = FALSE)
confint(ols_boot, type = "data")
```

---

cov\_control

*Tuning parameters for Huber M-estimation of location and scatter*

---

**Description**

Obtain a list with tuning paramters for [cov\\_Huber\(\)](#).

**Usage**

```
cov_control(prob = 0.95, max_iterations = 200, tol = 1e-07)
```

**Arguments**

prob	numeric; probability for the quantile of the $\chi^2$ distribution to be used as cutoff point in the Huber weight function (defaults to 0.95).
max_iterations	an integer giving the maximum number of iterations in the iteratively reweighted algorithm.
tol	a small positive numeric value to be used to determine convergence of the iteratively reweighted algorithm.

**Value**

A list with components corresponding to the arguments.

**Author(s)**

Andreas Alfons

**References**

Huber, P.J. (1981) *Robust Statistics*. John Wiley & Sons.

**See Also**

[cov\\_Huber\(\)](#)

**Examples**

```
data("BSG2014")

# run bootstrap test after winsorization
ctrl <- cov_control(prob = 0.95)
boot <- test_mediation(BSG2014,
  x = "ValueDiversity",
  y = "TeamCommitment",
  m = "TaskConflict",
  method = "covariance",
  control = ctrl)

summary(boot)
```

---

 cov\_Huber

---

*Huber M-estimator of location and scatter*


---

**Description**

Compute a Huber M-estimator of location and scatter, which is reasonably robust for a small number of variables.

**Usage**

```
cov_Huber(x, control = cov_control(...), ...)
```

**Arguments**

x	a numeric matrix or data frame.
control	a list of tuning parameters as generated by <code>cov_control()</code> .
...	additional arguments can be used to specify tuning parameters directly instead of via control.

**Details**

An iterative reweighting algorithm is used to compute the Huber M-estimator. The Huber weight function thereby corresponds to a convex optimization problem, resulting in a unique solution.

**Value**

An object of class "cov\_Huber" with the following components:

center	a numeric vector containing the location vector estimate.
cov	a numeric matrix containing the scatter matrix estimate.
prob	numeric; probability for the quantile of the $\chi^2$ distribution used as cutoff point in the Huber weight function.
weights	a numeric vector containing the relative robustness weights for the observations.
tau	numeric; correction for Fisher consistency under multivariate normal distributions.
converged	a logical indicating whether the iterative reweighting algorithm converged.
iterations	an integer giving the number of iterations required to obtain the solution.

**Author(s)**

Andreas Alfons

**References**

Huber, P.J. (1981) *Robust Statistics*. John Wiley & Sons.

Zu, J. and Yuan, K.-H. (2010) Local Influence and Robust Procedures for Mediation Analysis. *Multivariate Behavioral Research*, **45**(1), 1–44. doi:10.1080/00273170903504695.

**See Also**

`cov_control()`, `test_mediation()`, `fit_mediation()`



**Examples**

```
data("BSG2014")

# define variables
x <- "ValueDiversity"
y <- "TeamCommitment"
m <- "TaskConflict"

# compute Huber M-estimator
cov_Huber(BSG2014[, c(x, y, m)])
```

cov\_ML

*Maximum likelihood estimator of mean vector and covariance matrix***Description**

Compute the maximum likelihood estimator of the mean vector and the covariance matrix.

**Usage**

```
cov_ML(x, ...)
```

**Arguments**

x                    a numeric matrix or data frame.  
...                   additional arguments are currently ignored.

**Value**

An object of class "cov\_ML" with the following components:

center                a numeric vector containing the mean vector estimate.  
cov                    a numeric matrix containing the covariance matrix estimate.  
n                      an integer giving the number of observations.

**Author(s)**

Andreas Alfons

**References**

Zu, J. and Yuan, K.-H. (2010) Local Influence and Robust Procedures for Mediation Analysis. *Multivariate Behavioral Research*, **45**(1), 1–44. doi:10.1080/00273170903504695.

**See Also**

[test\\_mediation\(\)](#), [fit\\_mediation\(\)](#)

**Examples**

```
data("BSG2014")

# define variables
x <- "ValueDiversity"
y <- "TeamCommitment"
m <- "TaskConflict"

# compute Huber M-estimator
cov_ML(BSG2014[, c(x, y, m)])
```

density\_plot

*Density plot of the indirect effect(s)***Description**

Produce a density plot of the indirect effect(s) from (robust) mediation analysis. In addition to the density, a vertical line representing the point estimate and a shaded area representing the confidence interval are drawn.

**Usage**

```
density_plot(object, ...)

## Default S3 method:
density_plot(object, ...)

## S3 method for class 'sobel_test_mediation'
density_plot(object, grid = NULL, level = 0.95, ...)

## S3 method for class 'list'
density_plot(object, grid = NULL, level = 0.95, ...)

## S3 method for class 'setup_density_plot'
density_plot(object, ...)
```

**Arguments**

object	an object inheriting from class " <a href="#">test_mediation</a> " containing results from (robust) mediation analysis, or a list of such objects.
...	additional arguments to be passed down.
grid	an optional numeric vector containing the values at which to evaluate the assumed normal density from Sobel's test. The default is to take 512 equally spaced points between the estimated indirect effect $\pm$ three times the standard error according to Sobel's formula.

**level** numeric; the confidence level of the confidence intervals from Sobel's test. The default is to include 95% confidence intervals. Note that this is not used for bootstrap tests, as those require to specify the confidence level already in `test_mediation()`.

## Details

Methods first call `setup_density_plot()` to extract all necessary information to produce the plot, then the "setup\_density\_plot" method is called to produce the plot.

## Value

An object of class "ggplot".

## Author(s)

Andreas Alfons

## References

Alfons, A., Ates, N.Y. and Groenen, P.J.F. (2022) Robust Mediation Analysis: The R Package **robmed**. *Journal of Statistical Software*, **103**(13), 1–45. doi:10.18637/jss.v103.i13.

## See Also

`test_mediation()`, `setup_density_plot()`  
`ci_plot()`, `ellipse_plot()`, `weight_plot()`, `plot()`

## Examples

```
data("BSG2014")

# run fast-and-robust bootstrap test
robust_boot <- test_mediation(BSG2014,
                             x = "ValueDiversity",
                             y = "TeamCommitment",
                             m = "TaskConflict",
                             level = 0.9,
                             robust = TRUE)

# create plot for robust bootstrap test
density_plot(robust_boot)
density_plot(robust_boot, color = "#00BFC4", fill = "#00BFC4")

# run OLS bootstrap test
ols_boot <- test_mediation(BSG2014,
                           x = "ValueDiversity",
                           y = "TeamCommitment",
                           m = "TaskConflict",
                           level = 0.9,
                           robust = FALSE)
```

```
# compare robust and OLS bootstrap tests
boot_list <- list("OLS bootstrap" = ols_boot,
                 "ROBMED" = robust_boot)
density_plot(boot_list)

# the plot can be customized in the usual way
density_plot(boot_list) + theme_bw() +
  labs(title = "OLS bootstrap vs ROBMED")
```

---

ellipse\_plot

*Diagnostic plot with a tolerance ellipse*


---

### Description

Produce a scatter plot of two variables used in (robust) mediation analysis together with a tolerance ellipse. Exploiting the relationship between the regression coefficients and the covariance matrix, that tolerance ellipse illustrates how well the regression results represent the data. In addition, a line that visualizes the estimated regression coefficient is added when relevant.

### Usage

```
ellipse_plot(object, ...)

## Default S3 method:
ellipse_plot(
  object,
  horizontal = NULL,
  vertical = NULL,
  partial = FALSE,
  level = 0.975,
  npoints = 100,
  ...
)

## S3 method for class 'setup_ellipse_plot'
ellipse_plot(object, ...)
```

### Arguments

<code>object</code>	an object inheriting from class " <a href="#">fit_mediation</a> " or " <a href="#">test_mediation</a> " containing results from (robust) mediation analysis, or a list of such objects.
<code>...</code>	additional arguments to be passed down.
<code>horizontal</code>	a character string specifying the variable to be plotted on the horizontal axis. If the dependent variable is chosen for the vertical axis, a hypothesized mediator or an independent variable must be selected for the horizontal axis. If a hypothesized mediator is chosen for the vertical axis, an independent variable must be

	selected for the horizontal axis (in case of a serial multiple mediator model, a hypothesized mediator occurring earlier in the sequence is also allowed). The default is to plot the first independent variable on the horizontal axis.
vertical	a character string specifying the variable to be plotted on the vertical axis: the dependent variable or a hypothesized mediator. The default is to plot the first hypothesized mediator on the vertical axis.
partial	a logical indicating whether the vertical axis should display the observed values of the selected variable (FALSE), or the partial residuals with respect to the variable on the horizontal axis (TRUE). The latter allows to display the corresponding regression coefficient by a line.
level	numeric; the confidence level of the tolerance ellipse. It gives the percentage of observations that are expected to lie within the ellipse under the assumption of a normal distribution, and therefore it controls the size of the ellipse. The default is such that the ellipse is expected to contain 97.5% of the observations.
npoints	the number of grid points used to evaluate and draw the ellipse. The default is to use 100 grid points.

## Details

A line to visualize the corresponding regression coefficient is added if `partial = TRUE`, or in case of a simple mediation model (without control variables) when the hypothesized mediator is plotted on the vertical axis and the independent variable is plotted on the horizontal axis.

For robust estimation methods that return outlyingness weights for each data point, those weights are visualized by coloring the points on a grey scale. If a list of objects has been supplied and there are multiple objects from such robust methods, each method is placed in a separate panel.

Methods first call `setup_ellipse_plot()` to extract all necessary information to produce the plot, then the "setup\_ellipse\_plot" method is called to produce the plot.

## Value

An object of class "ggplot".

## Author(s)

Andreas Alfons

## References

Alfons, A., Ates, N.Y. and Groenen, P.J.F. (2022) Robust Mediation Analysis: The R Package **robmed**. *Journal of Statistical Software*, **103**(13), 1–45. doi:10.18637/jss.v103.i13.

## See Also

`fit_mediation()`, `test_mediation()`, `setup_ellipse_plot()`  
`ci_plot()`, `density_plot()`, `weight_plot()`, `plot()`

## Examples

```
data("BSG2014")

# obtain robust fit of mediation model
robust_fit <- fit_mediation(BSG2014,
  x = "ValueDiversity",
  y = "TeamCommitment",
  m = "TaskConflict",
  robust = TRUE)

# create plot for robust model fit
ellipse_plot(robust_fit)

# original data and partial residuals
ellipse_plot(robust_fit, horizontal = "TaskConflict",
  vertical = "TeamCommitment")
ellipse_plot(robust_fit, horizontal = "TaskConflict",
  vertical = "TeamCommitment", partial = TRUE)

# obtain OLS fit of mediation model
ols_fit <- fit_mediation(BSG2014,
  x = "ValueDiversity",
  y = "TeamCommitment",
  m = "TaskConflict",
  robust = FALSE)

# compare robust and OLS model fits
fit_list <- list("OLS bootstrap" = ols_fit,
  "ROBMED" = robust_fit)
ellipse_plot(fit_list)

# the plot can be customized in the usual way
ellipse_plot(fit_list) + theme_bw() +
  labs(title = "OLS vs robust estimation")
```

---

fit_mediation	<i>(Robustly) fit a mediation model</i>
---------------	---

---

## Description

(Robustly) estimate the effects in a mediation model.

## Usage

```
fit_mediation(object, ...)

## S3 method for class 'formula'
fit_mediation(formula, data, ...)
```

```
## Default S3 method:
fit_mediation(
  object,
  x,
  y,
  m,
  covariates = NULL,
  method = c("regression", "covariance"),
  robust = TRUE,
  family = "gaussian",
  model = c("parallel", "serial"),
  contrast = FALSE,
  fit_yx = TRUE,
  control = NULL,
  ...
)
```

## Arguments

<code>object</code>	the first argument will determine the method of the generic function to be dispatched. For the default method, this should be a data frame containing the variables.
<code>...</code>	additional arguments to be passed down. For the default method, this can be used to specify tuning parameters directly instead of via <code>control</code> .
<code>formula</code>	an object of class "formula" (or one that can be coerced to that class): a symbolic description of the model to be fitted. Hypothesized mediator variables should be wrapped in a call to <code>m()</code> (see examples), and any optional control variables should be wrapped in a call to <code>covariates()</code> .
<code>data</code>	for the formula method, a data frame containing the variables.
<code>x</code>	a character, integer or logical vector specifying the columns of object containing the independent variables of interest.
<code>y</code>	a character string, an integer or a logical vector specifying the column of object containing the dependent variable.
<code>m</code>	a character, integer or logical vector specifying the columns of object containing the hypothesized mediator variables.
<code>covariates</code>	optional; a character, integer or logical vector specifying the columns of object containing additional covariates to be used as control variables.
<code>method</code>	a character string specifying the method of estimation. Possible values are "regression" (the default) to estimate the effects via regressions, or "covariance" to estimate the effects via the covariance matrix. Note that the effects are always estimated via regressions if more than one independent variable or hypothesized mediator is specified, or if control variables are supplied.
<code>robust</code>	a logical indicating whether to robustly estimate the effects (defaults to TRUE). For estimation via regressions ( <code>method = "regression"</code> ), this can also be a character string, with "MM" specifying the MM-estimator of regression, and "median" specifying median regression.

family	a character string specifying the error distribution to be used in maximum likelihood estimation of regression models. Possible values are "gaussian" for a normal distribution (the default), <code>skewnormal</code> for a skew-normal distribution, "student" for Student's t distribution, "skewt" for a skew-t distribution, or "select" to select among these four distributions via BIC (see 'Details'). This is only relevant if <code>method = "regression"</code> and <code>robust = FALSE</code> .
model	a character string specifying the type of model in case of multiple mediators. Possible values are "parallel" (the default) for the parallel multiple mediator model, or "serial" for the serial multiple mediator model. This is only relevant for models with multiple hypothesized mediators, which are currently only implemented for estimation via regressions ( <code>method = "regression"</code> ).
contrast	a logical indicating whether to compute pairwise contrasts of the indirect effects (defaults to FALSE). This can also be a character string, with "estimates" for computing the pairwise differences of the indirect effects, and "absolute" for computing the pairwise differences of the absolute values of the indirect effects. This is only relevant for models with multiple indirect effects, which are currently only implemented for estimation via regressions ( <code>method = "regression"</code> ). For models with multiple independent variables of interest and multiple hypothesized mediators, contrasts are only computed between indirect effects corresponding to the same independent variable.
fit_yx	a logical indicating whether to fit the regression model $y \sim x + \text{covariates}$ to estimate the total effect (the default is TRUE). This is only relevant if <code>method = "regression"</code> and <code>robust = FALSE</code> .
control	a list of tuning parameters for the corresponding robust method. For the robust MM-estimator of regression ( <code>method = "regression"</code> , and <code>robust = TRUE</code> or <code>robust = "MM"</code> ), a list of tuning parameters for <code>lmrob()</code> as generated by <code>MM_reg_control()</code> . For median regression ( <code>method = "regression"</code> , and <code>robust = "median"</code> ), a list of tuning parameters for <code>rq()</code> as generated by <code>median_reg_control()</code> . For winsorized covariance matrix estimation ( <code>method = "covariance"</code> and <code>robust = TRUE</code> ), a list of tuning parameters for <code>cov_Huber()</code> as generated by <code>cov_control()</code> .

## Details

With `method = "regression"`, and `robust = TRUE` or `robust = "MM"`, the effects are computed via the robust MM-estimator of regression from `lmrob()`. This is the default behavior.

With `method = "regression"` and `robust = "median"`, the effects are estimated via median regressions with `rq()`. Unlike the robust MM-regressions above, median regressions are not robust against outliers in the explanatory variables.

With `method = "regression"`, `robust = FALSE` and `family = "select"`, the error distribution to be used in maximum likelihood estimation of the regression models is selected via BIC. The following error distributions are included in the selection procedure: a normal distribution, a skew-normal distribution, Student's t distribution, and a skew-t distribution. Note that the parameters of those distributions are estimated as well. The skew-normal and skew-t distributions thereby use a centered parametrization such that the residuals are (approximately) centered around 0. Moreover, the skew-t distribution is only evaluated in the selection procedure if both the skew-normal and Student's t distribution yield an improvement in BIC over the normal distribution. Otherwise the estimation with a skew-t error distribution can be unstable. Furthermore, this saves a considerable



amount of computation time in a bootstrap test, as estimation with those error distributions is orders of magnitude slower than any other implemented estimation procedure.

With `method = "covariance"` and `robust = TRUE`, the effects are estimated based on a Huber M-estimator of location and scatter. Note that this covariance-based approach is less robust than the approach based on robust MM-regressions described above.

## Value

An object inheriting from class `"fit_mediation"` (class `"reg_fit_mediation"` if `method = "regression"` or `"cov_fit_mediation"` if `method = "covariance"`) with the following components:

<code>a</code>	a numeric vector containing the point estimates of the effects of the independent variables on the proposed mediator variables.
<code>b</code>	a numeric vector containing the point estimates of the direct effects of the proposed mediator variables on the dependent variable.
<code>d</code>	in case of a serial multiple mediator model, a numeric vector containing the point estimates of the effects of proposed mediator variables on other mediator variables occurring later in the sequence (only <code>"reg_fit_mediation"</code> if applicable).
<code>total</code>	a numeric vector containing the point estimates of the total effects of the independent variables on the dependent variable.
<code>direct</code>	a numeric vector containing the point estimates of the direct effects of the independent variables on the dependent variable.
<code>indirect</code>	a numeric vector containing the point estimates of the indirect effects.
<code>ab</code>	for back-compatibility with versions <0.10.0, the point estimates of the indirect effects are also included here. <b>This component is deprecated and may be removed as soon as the next version.</b>
<code>fit_mx</code>	an object of class <code>"lmrob"</code> , <code>"rq"</code> , <code>"lm"</code> or <code>"lmse"</code> containing the estimation results from the regression of the proposed mediator variable on the independent variables, or a list of such objects in case of more than one hypothesized mediator (only <code>"reg_fit_mediation"</code> ).
<code>fit_ymx</code>	an object of class <code>"lmrob"</code> , <code>"rq"</code> , <code>"lm"</code> or <code>"lmse"</code> containing the estimation results from the regression of the dependent variable on the proposed mediator and independent variables (only <code>"reg_fit_mediation"</code> ).
<code>fit_yx</code>	an object of class <code>"lm"</code> or <code>"lmse"</code> containing the estimation results from the regression of the dependent variable on the independent variables (only <code>"reg_fit_mediation"</code> if arguments <code>robust = FALSE</code> and <code>fit_yx = TRUE</code> were used).
<code>cov</code>	an object of class <code>"cov_Huber"</code> or <code>"cov_ML"</code> containing the covariance matrix estimates (only <code>"cov_fit_mediation"</code> ).
<code>x, y, m, covariates</code>	character vectors specifying the respective variables used.
<code>data</code>	a data frame containing the independent, dependent and proposed mediator variables, as well as covariates.
<code>robust</code>	either a logical indicating whether the effects were estimated robustly, or one of the character strings <code>"MM"</code> and <code>"median"</code> specifying the type of robust regressions.

model	a character string specifying the type of mediation model fitted: "simple" in case of one independent variable and one hypothesized mediator, "multiple" in case of multiple independent variables and one hypothesized mediator, "parallel" in case of parallel multiple mediators, or "serial" in case of serial multiple mediators (only "reg_fit_mediation").
contrast	either a logical indicating whether contrasts of the indirect effects were computed, or one of the character strings "estimates" and "absolute" specifying the type of contrasts of the indirect effects (only "reg_fit_mediation").
control	a list of tuning parameters used (if applicable).

### Mediation models

The following mediation models are implemented. In the regression equations below, the  $i_j$  are intercepts and the  $e_j$  are random error terms.

- *Simple mediation model*: The mediation model in its simplest form is given by the equations

$$\begin{aligned}
 M &= i_1 + aX + e_1, \\
 Y &= i_2 + bM + cX + e_2, \\
 Y &= i_3 + c'X + e_3,
 \end{aligned}$$

where  $Y$  denotes the dependent variable,  $X$  the independent variable, and  $M$  the hypothesized mediator. The main parameter of interest is the product of coefficients  $ab$ , called the indirect effect. The coefficients  $c$  and  $c'$  are called the direct and total effect, respectively.

- *Parallel multiple mediator model*: The simple mediation model can be extended with multiple mediators  $M_1, \dots, M_k$  in the following way:

$$\begin{aligned}
 M_1 &= i_1 + a_1X + e_1, \\
 &\vdots \\
 M_k &= i_k + a_kX + e_k, \\
 Y &= i_{k+1} + b_1M_1 + \dots + b_kM_k + cX + e_{k+1}, \\
 Y &= i_{k+2} + c'X + e_{k+2}.
 \end{aligned}$$

The main parameters of interest are the individual indirect effects  $a_1b_1, \dots, a_kb_k$ .

- *Serial multiple mediator model*: It differs from the parallel multiple mediator model in that it allows the hypothesized mediators  $M_1, \dots, M_k$  to influence each other in a sequential manner. It is given by the equations

$$\begin{aligned}
 M_1 &= i_1 + a_1X + e_1, \\
 M_2 &= i_1 + d_{21}M_1 + a_2X + e_2, \\
 &\vdots \\
 M_k &= i_k + d_{k1}M_1 + \dots + d_{k,k-1}M_{k-1} + a_kX + e_k, \\
 Y &= i_{k+1} + b_1M_1 + \dots + b_kM_k + cX + e_{k+1}, \\
 Y &= i_{k+2} + c'X + e_{k+2}.
 \end{aligned}$$

The serial multiple mediator model quickly grows in complexity with increasing number of mediators due to the combinatorial increase in indirect paths through the mediators. It is therefore only implemented for two and three mediators to maintain a focus on easily interpretable models. For two serial mediators, the three indirect effects  $a_1b_1$ ,  $a_2b_2$ , and  $a_1d_{21}b_2$  are the main parameters of interest. For three serial mediators, there are already seven indirect effects:  $a_1b_1$ ,  $a_2b_2$ ,  $a_3b_3$ ,  $a_1d_{21}b_2$ ,  $a_1d_{31}b_3$ ,  $a_2d_{32}b_3$ , and  $a_1d_{21}d_{32}b_3$ .

- *Multiple independent variables to be mediated:* The simple mediation model can also be extended by allowing multiple independent variables  $X_1, \dots, X_l$  instead of multiple mediators. It is defined by the equations

$$\begin{aligned} M &= i_1 + a_1X_1 + \dots + a_lX_l + e_1, \\ Y &= i_2 + bM + c_1X_1 + \dots + c_lX_l + e_2, \\ Y &= i_3 + c'_1X_1 + \dots + c'_lX_l + e_3. \end{aligned}$$

The indirect effects  $a_1b, \dots, a_lb$  are the main parameters of interest. Note that an important special case of this model occurs when a categorical independent variable is represented by a group of dummy variables.

- *Control variables:* To isolate the effects of the independent variables of interest from other factors, control variables can be added to all regression equations of a mediation model. Note that there is no intrinsic difference between independent variables of interest and control variables in terms of the model or its estimation. The difference is purely conceptual in nature: for the control variables, the estimates of the direct and indirect paths are not of particular interest to the researcher. Control variables can therefore be specified separately from the independent variables of interest. Only for the latter, results for the indirect effects are included in the output.
- *More complex models:* Some of the models described above can be combined, for instance parallel and serial multiple mediator models support multiple independent variables of interest and control variables.

## Note

The default method takes a data frame its first argument so that it can easily be used with the pipe operator (R's built-in `|>` or **magrittr**'s `%>%`).

## Author(s)

Andreas Alfons

## References

- Alfons, A., Ates, N.Y. and Groenen, P.J.F. (2022a) A Robust Bootstrap Test for Mediation Analysis. *Organizational Research Methods*, **25**(3), 591–617. doi:10.1177/1094428121999096.
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- Azzalini, A. and Arellano-Valle, R. B. (2013) Maximum Penalized Likelihood Estimation for Skew-Normal and Skew-t Distributions. *Journal of Statistical Planning and Inference*, **143**(2), 419–433. doi:10.1016/j.jspi.2012.06.022.

Yuan, Y. and MacKinnon, D.P. (2014) Robust Mediation Analysis Based on Median Regression. *Psychological Methods*, **19**(1), 1–20. doi:10.1037/a0033820.

Zu, J. and Yuan, K.-H. (2010) Local Influence and Robust Procedures for Mediation Analysis. *Multivariate Behavioral Research*, **45**(1), 1–44. doi:10.1080/00273170903504695.

### See Also

`test_mediation()`  
`lmrob()`, `lm()`, `cov_Huber()`, `cov_ML()`

### Examples

```
data("BSG2014")

## seed to be used for the random number generator
seed <- 20150601

## simple mediation
set.seed(seed)
fit_simple <- fit_mediation(TeamCommitment ~
                           m(TaskConflict) +
                           ValueDiversity,
                           data = BSG2014)
boot_simple <- test_mediation(fit_simple)
summary(boot_simple)

# depending on the seed of the random number generator, one
# may get a p value slightly below or above the arbitrary
# 5% threshold
p_value(boot_simple, parm = "indirect")

# The results in Alfons et al. (2022a) were obtained with an
# older version of the random number generator and with BCa
# bootstrap intervals (which are no longer recommended).
# To reproduce those results, uncomment the lines below.
# RNGversion("3.5.3")
# set.seed(seed)
# fit_simple <- fit_mediation(TeamCommitment ~
#                             m(TaskConflict) +
#                             ValueDiversity,
#                             data = BSG2014)
# boot_simple <- test_mediation(fit_simple, type = "bca")
# summary(boot_simple)

## serial multiple mediators
set.seed(seed)
fit_serial <- fit_mediation(TeamScore ~
                           serial_m(TaskConflict,
                                     TeamCommitment) +
                           ValueDiversity,
                           data = BSG2014)
```

```

boot_serial <- test_mediation(fit_serial, level = 0.9)
summary(boot_serial)

## parallel multiple mediators and control variables
set.seed(seed)
fit_parallel <- fit_mediation(TeamPerformance ~
                             parallel_m(ProceduralJustice,
                                           InteractionalJustice) +
                             SharedLeadership +
                             covariates(AgeDiversity,
                                           GenderDiversity),
                             data = BSG2014)
boot_parallel <- test_mediation(fit_parallel)
summary(boot_parallel)

```

m

*Create an object of hypothesized mediators or control variables***Description**

`m()` and its wrappers `parallel_m()` and `serial_m()` create an object of hypothesized mediators, while `covariates()` creates an object of control variables. Usually, these are used in a formula specifying a mediation model.

**Usage**

```

m(..., .model = c("parallel", "serial"))

parallel_m(...)

serial_m(...)

covariates(...)

```

**Arguments**

<code>...</code>	variables are supplied as arguments, as usual separated by a comma.
<code>.model</code>	a character string specifying the type of model in case of multiple mediators. Possible values are "parallel" (the default) for the parallel multiple mediator model, or "serial" for the serial multiple mediator model.

**Details**

`m()` and `covariates()` are essentially wrappers for `cbind()` with a specific class prepended to the class(es) of the resulting object.

`parallel_m()` and `serial_m()` are wrappers for `m()` with the respective value for argument `.model`.

**Value**

`m()` returns an object inheriting from class "mediators" (with subclass "parallel\_mediators" or "serial\_mediators" as specified by argument `.model`), and `covariates()` returns an object of class "covariates". Typically, these inherit from class "matrix".

**Author(s)**

Andreas Alfons

**See Also**

`fit_mediation()`, `test_mediation()`

**Examples**

```
data("BSG2014")

# inside formula
fit_mediation(TeamCommitment ~ m(TaskConflict) + ValueDiversity,
              data = BSG2014)

# outside formula
mediator <- with(BSG2014, m(TaskConflict))
fit_mediation(TeamCommitment ~ mediator + ValueDiversity,
              data = BSG2014)
```

---

plot-methods

*Plot (robust) mediation analysis results*

---

**Description**

Visualize results from (robust) mediation analysis.

**Usage**

```
## S3 method for class 'fit_mediation'
autoplot(object, which = c("ellipse", "weight"), ...)

## S3 method for class 'test_mediation'
autoplot(object, which = c("ci", "density", "ellipse", "weight"), ...)

## S3 method for class 'fit_mediation'
plot(x, which = c("ellipse", "weight"), ...)

## S3 method for class 'test_mediation'
plot(x, which = c("ci", "density", "ellipse", "weight"), ...)
```

**Arguments**

<code>object, x</code>	an object inheriting from class <code>"fit_mediation"</code> or <code>"test_mediation"</code> containing results from (robust) mediation analysis.
<code>which</code>	a character string specifying which plot to produce. Possible values are <code>"ci"</code> for a dot plot of selected effects together with confidence intervals (see <code>ci_plot()</code> ), <code>"density"</code> for a density plot of the indirect effect(s) (see <code>density_plot()</code> ), <code>"ellipse"</code> for a diagnostic plot of the data together with a tolerance ellipse (see <code>ellipse_plot()</code> ), and <code>"weight"</code> for a diagnostic plot of robust regression weights (see <code>weight_plot()</code> ).
<code>...</code>	additional arguments to be passed down.

**Details**

The `"fit_mediation"` method calls `ellipse_plot()` or `weight_plot()`, depending on the argument `which`.

The `"test_mediation"` method calls `ci_plot()`, `density_plot()`, `ellipse_plot()`, or `weight_plot()`, depending on the argument `which`.

**Value**

An object of class `"ggplot"`.

**Author(s)**

Andreas Alfons

**References**

Alfons, A., Ates, N.Y. and Groenen, P.J.F. (2022) Robust Mediation Analysis: The R Package **robmed**. *Journal of Statistical Software*, **103**(13), 1–45. doi:10.18637/jss.v103.i13.

**See Also**

`fit_mediation()`, `test_mediation()`  
`ci_plot()`, `density_plot()`, `ellipse_plot()`, `weight_plot()`

**Examples**

```
data("BSG2014")

# run fast-and-robust bootstrap test
boot <- test_mediation(BSG2014,
  x = "ValueDiversity",
  y = "TeamCommitment",
  m = "TaskConflict",
  level = 0.9)

# create plots for robust bootstrap test
plot(boot, which = "ci")
```

```
plot(boot, which = "density")
plot(boot, which = "ellipse")
plot(boot, which = "weight")
```

p\_value

*p-Values from (robust) mediation analysis*

## Description

Compute or extract the p-values for effects in (robust) mediation analysis.

## Usage

```
p_value(object, ...)

## S3 method for class 'boot_test_mediation'
p_value(object, parm = NULL, type = c("boot", "data"), digits = 4L, ...)

## S3 method for class 'sobel_test_mediation'
p_value(object, parm = NULL, ...)
```

## Arguments

object	an object inheriting from class <code>"test_mediation"</code> containing results from (robust) mediation analysis.
...	for the generic function, additional arguments to be passed down to methods. For the methods, additional arguments are currently ignored.
parm	an integer, character or logical vector specifying the paths for which to extract or compute p-values, or NULL to extract or compute p-values for all coefficients. In case of a character vector, possible values are "a", "b", "d" (only serial multiple mediator models), "total", "direct", and "indirect".
type	a character string specifying how to compute the p-values of the effects other than the indirect effect(s). Possible values are "boot" (the default) to compute bootstrap p-values using the normal approximation (i.e., to assume a normal distribution of the corresponding effect with the standard deviation computed from the bootstrap replicates), or "data" to compute p-values via statistical theory based on the original data (e.g., based on a t-distribution if the coefficients are estimated via regression). Note that this is only relevant for mediation analysis via a bootstrap test, where the p-value of the indirect effect is always computed as described in 'Details'.
digits	an integer determining how many digits to compute for the p-values of the indirect effects (see 'Details'). The default is to compute 4 digits after the comma.



### Details

For bootstrap tests, the p-value of the indirect effect is computed as the smallest significance level  $\alpha$  for which the  $(1 - \alpha) * 100\%$  confidence interval obtained from the bootstrapped distribution does not contain 0.

This is a simple implementation, where each digit after the comma is determined via a grid search. Hence computation time can be long if confidence intervals are computed via the bias-corrected and accelerated method ("bca").

For Sobel tests, the p-value of the indirect effect is already stored in the object returned by `test_mediation()` and is simply extracted.

### Value

A numeric vector containing the requested p-values.

### Author(s)

Andreas Alfons

### See Also

`test_mediation()`, `coef()`, `confint()`

### Examples

```
data("BSG2014")
boot <- test_mediation(BSG2014,
  x = "ValueDiversity",
  y = "TeamCommitment",
  m = "TaskConflict",
  level = 0.9)
p_value(boot)
```

---

reg\_control

*Tuning parameters for robust regression*


---

### Description

Obtain a list with tuning parameters for the robust MM-estimator of regression from `lmrob()` or median regression from `rq()`.

**Usage**

```
reg_control(efficiency = 0.85, max_iterations = 200, tol = 1e-07, seed = NULL)
```

```
MM_reg_control(
  efficiency = 0.85,
  max_iterations = 200,
  tol = 1e-07,
  seed = NULL
)
```

```
median_reg_control(algorithm = "br")
```

**Arguments**

efficiency	a numeric value giving the desired efficiency (defaults to 0.85 for 85% efficiency).
max_iterations	an integer giving the maximum number of iterations in various parts of the algorithm.
tol	a small positive numeric value to be used to determine convergence in various parts of the algorithm.
seed	optional initial seed for the random number generator (see <a href="#">.Random.seed</a> ).
algorithm	a character string specifying the algorithm for computing the median regression fit. See argument method in <a href="#">rq()</a> for options. If you experience an infinite loop with the default algorithm ("br"), you may want to try "fn".

**Details**

Prior to version 1.2.0, the MM-estimator of regression was the only type of robust regression in **robmed** that supported control parameters. Starting with version 1.2.0, control parameters can also be passed to median regression, specifically the type of algorithm to be used. Function `reg_control()` is an alias for `MM_reg_control()` for backwards compatibility, but it is now recommended to use `MM_reg_control()` when performing MM-regression and `median_reg_control()` when performing median regression.

**Value**

For `MM_reg_control()` and `reg_control()`, a list of control parameters for the MM-estimator of regression as returned by [lmrob.control\(\)](#).

For `median_reg_control()`, a list of control parameters for median regression.

**Note**

`MM_reg_control()` and its alias `reg_control()` is a simplified wrapper function for [lmrob.control\(\)](#), as the latter requires detailed knowledge of the algorithm for the MM-estimator of regression. Currently only 95%, 90%, 85% (the default) and 80% efficiency are supported. For other values, please specify the corresponding tuning parameters in [lmrob.control\(\)](#) directly.

**Author(s)**

Andreas Alfons

**References**

Salibian-Barrera, M. and Yohai, V.J. (2006) A Fast Algorithm for S-regression Estimates. *Journal of Computational and Graphical Statistics*, **15**(2), 414–427. doi:10.1198/106186006x113629.

Yohai, V.J. (1987) High Breakdown-Point and High Efficiency Estimates for Regression. *The Annals of Statistics*, **15**(20), 642–656. doi:10.1214/aos/1176350366.

Koenker, R.W. (2005) *Quantile Regression*. Cambridge University Press.

**See Also**

[lmrob\(\)](#), [lmrob.control\(\)](#)

**Examples**

```
data("BSG2014")

# run fast-and-robust bootstrap test
ctrl <- MM_reg_control(efficiency = 0.95)
boot <- test_mediation(BSG2014,
  x = "ValueDiversity",
  y = "TeamCommitment",
  m = "TaskConflict",
  level = 0.9,
  control = ctrl)

summary(boot)
```

---

retest

*Retest for mediation*


---

**Description**

Re-perform a test for the indirect effect(s) based on results from (robust) mediation analysis. This function is purely available for computational convenience if the analysis was accidentally run with the wrong parameter settings, as it avoids having to re-run the bootstrap procedure. It must not be abused for *p*-hacking.

**Usage**

```
retest(object, ...)

## S3 method for class 'boot_test_mediation'
retest(object, alternative, level, type, contrast, ...)

## S3 method for class 'sobel_test_mediation'
retest(object, alternative, order, ...)
```

**Arguments**

<code>object</code>	an object inheriting from class " <code>test_mediation</code> " containing results from (robust) mediation analysis.
<code>...</code>	additional arguments to be passed down to methods.
<code>alternative</code>	a character string specifying the alternative hypothesis in the test for the indirect effect. Possible values are "twosided", "less" or "greater".
<code>level</code>	numeric; the confidence level of the confidence interval in the bootstrap test.
<code>type</code>	a character string specifying the type of confidence interval to be computed in the bootstrap test. Possible values are "perc" for the percentile bootstrap, or "bca" for the bias-corrected and accelerated (BCa) bootstrap.
<code>contrast</code>	a logical indicating whether to compute pairwise contrasts of the indirect effects. This can also be a character string, with "estimates" for computing the pairwise differences of the indirect effects (such that it is tested whether two indirect effects are equal), and "absolute" for computing the pairwise differences of the absolute values of the indirect effects (such that it is tested whether two indirect effects are equal in magnitude). This is only relevant for models with multiple indirect effects, which are currently only implemented for bootstrap tests and estimation via regressions.
<code>order</code>	a character string specifying the order of approximation of the standard error in Sobel's test. Possible values are "first" for a first-order approximation, and "second" for a second-order approximation.

**Value**

An object of the same class as `object` with updated test results (see `test_mediation()`).

**Note**

From version 0.9.0 onwards, the behavior of this function changed. For arguments that are not supplied, the corresponding values of `object` are now used as defaults.

Since version 1.1.0, bias-corrected and accelerated (BCa) bootstrap confidence intervals are no longer recommended, and the option `type = "bca"` may disappear in the future.

**Author(s)**

Andreas Alfons

**See Also**

`test_mediation()`

**Examples**

```
data("BSG2014")

# run fast-and-robust bootstrap test
boot <- test_mediation(BSG2014,
```

```

      x = "SharedLeadership",
      y = "TeamPerformance",
      m = c("ProceduralJustice",
            "InteractionalJustice"),
      covariates = c("AgeDiversity",
                    "GenderDiversity"))

summary(boot)

# now include comparison of indirect effects
retest(boot, contrast = "estimates")

```

---

setup\_ci\_plot

---

Set up information for a dot plot with confidence intervals

---

## Description

Extract the relevant information for a dot plot with confidence intervals of selected effects from (robust) mediation analysis. Information on p-values of the selected effects can be included in addition to confidence intervals.

## Usage

```

setup_ci_plot(object, ...)

## S3 method for class 'boot_test_mediation'
setup_ci_plot(
  object,
  parm = c("direct", "indirect"),
  type = c("boot", "data"),
  p_value = FALSE,
  digits = 4L,
  ...
)

## S3 method for class 'sobel_test_mediation'
setup_ci_plot(
  object,
  parm = c("direct", "indirect"),
  level = 0.95,
  p_value = FALSE,
  ...
)

## S3 method for class 'list'
setup_ci_plot(object, ...)

```

## Arguments

object	an object inheriting from class " <code>test_mediation</code> " containing results from (robust) mediation analysis, or a list of such objects.
...	additional arguments to be passed down.
parm	an integer, character or logical vector specifying which effects to include in the plot. In case of a character vector, possible values are "a", "b", "d" (only serial multiple mediator models), "total", "direct", and "indirect". The default is to include the direct and the indirect effect(s).
type	a character string specifying which point estimates and confidence intervals to plot: those based on the bootstrap distribution ("boot"; the default), or those based on the original data ("data"). If "boot", the confidence intervals of effects other than the indirect effect(s) are computed using a normal approximation (i.e., assuming a normal distribution of the corresponding effect with the standard deviation computed from the bootstrap replicates). If "data", the confidence intervals of effects other than the indirect effect(s) are computed via statistical theory based on the original data (e.g., based on a t-distribution if the coefficients are estimated via regression). Note that this is only relevant for mediation analysis via a bootstrap test, where the confidence interval of the indirect effect is always computed via a percentile-based method due to the asymmetry of its distribution.
p_value	a logical indicating whether to include information on the p-values in addition to the confidence intervals. The default is FALSE.
digits	an integer determining how many digits to compute for bootstrap p-values of the indirect effects (see <code>p_value()</code> ). The default is to compute 4 digits after the comma. This is only relevant if <code>p_value = TRUE</code> .
level	numeric; the confidence level of the confidence intervals from Sobel's test. The default is to include 95% confidence intervals. Note that this is not used for bootstrap tests, as those require to specify the confidence level already in <code>test_mediation()</code> .

## Details

This function is used internally by `ci_plot()`. It may also be useful for users who want to produce a similar plot, but who want more control over what information to display or how to display that information.

## Value

An object of class "`setup_ci_plot`" with the following components:

ci	a data frame consisting of column <code>Effect</code> indicating the different effects, column <code>Estimate</code> containing the point estimates, column <code>Lower</code> for the lower confidence limit, and column <code>Upper</code> for the upper confidence limit. If argument <code>p_value = TRUE</code> , there is an additional column <code>Label</code> which gives the default facet label for the confidence intervals. If a list of " <code>test_mediation</code> " objects has been supplied, there is also a column <code>Method</code> , which takes the names or indices of the list elements to indicate the different methods.
----	---

p_value	a data frame consisting of column <code>Label</code> which gives the default facet label for the p-values, column <code>Effect</code> indicating the different effects, and column <code>Value</code> containing the p-values. If a list of " <code>test_mediation</code> " objects has been supplied, there is also a column <code>Method</code> , which takes the names or indices of the list elements to indicate the different methods. This is only returned if argument <code>p_value = TRUE</code> .
level	numeric; the confidence level used for the confidence intervals of the indirect effect(s).
have_methods	a logical indicating whether a list of " <code>test_mediation</code> " objects has been supplied. If <code>TRUE</code> , the data frame in the <code>ci</code> component contains a column <code>Method</code> .

**Author(s)**

Andreas Alfons

**References**

Alfons, A., Ates, N.Y. and Groenen, P.J.F. (2022) Robust Mediation Analysis: The R Package **robmed**. *Journal of Statistical Software*, **103**(13), 1–45. doi:10.18637/jss.v103.i13.

**See Also**

`test_mediation()`, `ci_plot()`

**Examples**

```
data("BSG2014")

# run fast-and-robust bootstrap test
boot <- test_mediation(BSG2014,
  x = "ValueDiversity",
  y = "TeamCommitment",
  m = "TaskConflict",
  level = 0.9)

# set up information for plot
setup <- setup_ci_plot(boot, parm = "Indirect")

# plot only density and confidence interval
ggplot() +
  geom_hline(yintercept = 0, color = "darkgrey") +
  geom_pointrange(aes(x = "Robust bootstrap", y = Estimate,
    ymin = Lower, ymax = Upper),
    data = setup$ci) +
  labs(x = NULL, y = "Indirect effect")
```

---

setup_density_plot	<i>Set up information for a density plot of the indirect effect(s)</i>
--------------------	--

---

## Description

Extract the relevant information for a density plot of the indirect effect(s) from results of (robust) mediation analysis.

## Usage

```
setup_density_plot(object, ...)

## S3 method for class 'boot_test_mediation'
setup_density_plot(object, ...)

## S3 method for class 'sobel_test_mediation'
setup_density_plot(object, grid = NULL, level = 0.95, ...)

## S3 method for class 'list'
setup_density_plot(object, ...)
```

## Arguments

object	an object inheriting from class " <a href="#">test_mediation</a> " containing results from (robust) mediation analysis, or a list of such objects.
...	additional arguments to be passed down.
grid	an optional numeric vector containing the values at which to evaluate the assumed normal density from Sobel's test. The default is to take 512 equally spaced points between the estimated indirect effect $\pm$ three times the standard error according to Sobel's formula.
level	numeric; the confidence level of the confidence intervals from Sobel's test. The default is to include 95% confidence intervals. Note that this is not used for bootstrap tests, as those require to specify the confidence level already in <a href="#">test_mediation()</a> .

## Details

This function is used internally by [density\\_plot\(\)](#). It may also be useful for users who want to produce a similar plot, but who want more control over what information to display or how to display that information.

## Value

An object of class "setup\_density\_plot" with the following components:



density	a data frame containing the values of the indirect effect where the density is estimated (column Indirect), and the estimated density values (column Density). In case of a model with multiple indirect effects, there is a column Effect that indicates the different indirect effects. If a list of " <a href="#">test_mediation</a> " objects has been supplied, there is also a column Method, which takes the names or indices of the list elements to indicate the different methods.
ci	a data frame consisting of column Estimate containing the point estimates, column Lower for the lower confidence limit, and column Upper for the upper confidence limit. In case of a model with multiple indirect effects, there is a column Effect that indicates the different indirect effects. If a list of " <a href="#">test_mediation</a> " objects has been supplied, there is also a column Method, which takes the names or indices of the list elements to indicate the different methods.
test	a character string indicating whether the object contains results from a bootstrap test ("boot") or a Sobel test ("sobel"), or a vector of such character strings if a list of " <a href="#">test_mediation</a> " objects has been supplied.
level	numeric; the confidence level used for the confidence intervals of the indirect effect(s).
have_effects	a logical indicating whether the mediation model contains multiple indirect effects. If TRUE, the data frames in the density and ci components contain a column Effect.
have_methods	a logical indicating whether a list of " <a href="#">test_mediation</a> " objects has been supplied. If TRUE, the data frames in the density and ci components contain a column Method.

**Author(s)**

Andreas Alfons

**References**

Alfons, A., Ates, N.Y. and Groenen, P.J.F. (2022) Robust Mediation Analysis: The R Package **robmed**. *Journal of Statistical Software*, **103**(13), 1–45. doi:10.18637/jss.v103.i13.

**See Also**

[test\\_mediation\(\)](#), [density\\_plot\(\)](#)

**Examples**

```
data("BSG2014")

# run fast-and-robust bootstrap test
boot <- test_mediation(BSG2014,
  x = "ValueDiversity",
  y = "TeamCommitment",
  m = "TaskConflict",
  level = 0.9)
```

```
# set up information for plot
setup <- setup_density_plot(boot)

# plot only density and confidence interval
ggplot() +
  geom_density(aes(x = Indirect, y = Density), data = setup$density,
               stat = "identity") +
  geom_rect(aes(xmin = Lower, xmax = Upper,
               ymin = -Inf, ymax = Inf),
            data = setup$ci, color = NA, alpha = 0.2) +
  labs(x = "Indirect effect", y = "Bootstrap density")
```

---

setup_ellipse_plot	<i>Set up a diagnostic plot with a tolerance ellipse</i>
--------------------	--

---

### Description

Extract the relevant information for a diagnostic plot with a tolerance ellipse from results of (robust) mediation analysis.

### Usage

```
setup_ellipse_plot(object, ...)

## S3 method for class 'test_mediation'
setup_ellipse_plot(object, ...)

## S3 method for class 'reg_fit_mediation'
setup_ellipse_plot(
  object,
  horizontal = NULL,
  vertical = NULL,
  partial = FALSE,
  level = 0.975,
  npoints = 100,
  ...
)

## S3 method for class 'cov_fit_mediation'
setup_ellipse_plot(
  object,
  horizontal = NULL,
  vertical = NULL,
  partial = FALSE,
  level = 0.975,
  npoints = 100,
  ...
)
```

```
)

## S3 method for class 'list'
setup_ellipse_plot(object, ...)
```

### Arguments

object	an object inheriting from class " <code>fit_mediation</code> " or " <code>test_mediation</code> " containing results from (robust) mediation analysis, or a list of such objects.
...	additional arguments to be passed down.
horizontal	a character string specifying the variable to be plotted on the horizontal axis. If the dependent variable is chosen for the vertical axis, a hypothesized mediator or an independent variable must be selected for the horizontal axis. If a hypothesized mediator is chosen for the vertical axis, an independent variable must be selected for the horizontal axis (in case of a serial multiple mediator model, a hypothesized mediator occurring earlier in the sequence is also allowed). The default is to plot the first independent variable on the horizontal axis.
vertical	a character string specifying the variable to be plotted on the vertical axis: the dependent variable or a hypothesized mediator. The default is to plot the first hypothesized mediator on the vertical axis.
partial	a logical indicating whether to extract the observed values of the selected variable for the vertical axis (FALSE), or the partial residuals with respect to the variable on the horizontal axis (TRUE). The latter allows to display the corresponding regression coefficient by a line.
level	numeric; the confidence level of the tolerance ellipse. It gives the percentage of observations that are expected to lie within the ellipse under the assumption of a normal distribution, and therefore it controls the size of the ellipse. The default is such that the ellipse is expected to contain 97.5% of the observations.
npoints	the number of grid points used to evaluate the ellipse. The default is to use 100 grid points.

### Details

This function is used internally by `ellipse_plot()`. It may also be useful for users who want to produce a similar plot, but who want more control over what information to display or how to display that information.

### Value

An object of class "`setup_ellipse_plot`" with the following components:

data	a data frame containing the coordinates of the data points to be plotted on the horizontal axis (column <code>x</code> ) and the coordinates on the vertical axis (column <code>y</code> ). For robust methods that assign outlyingness weights to each data point, those weights are given in column <code>Weight</code> . If a list of objects has been supplied and there are multiple objects from such robust methods, or if partial residuals are to be plotted on the vertical axis, there is also a column <code>Method</code> , which takes the names or indices of the list elements to indicate the different methods.
------	---

ellipse	a data frame containing the coordinates of the tolerance ellipse on the horizontal axis (column x) and on the vertical axis (column y). If a list of objects has been supplied, there is also a column Method, which takes the names or indices of the list elements to indicate the different methods.
line	a data frame with columns intercept and slope containing the intercept and slope, respectively, of the regression line to be plotted. If a list of objects has been supplied, there is also a column Method, which takes the names or indices of the list elements to indicate the different methods. This is only returned if partial = TRUE, or in case of a simple mediation model (without control variables) when the hypothesized mediator is plotted on the vertical axis and the independent variable is plotted on the horizontal axis.
horizontal	a character string giving the variable to be plotted on the horizontal axis.
vertical	a character string giving the variable to be plotted on the vertical axis
partial	a logical indicating whether the values to be plotted on the vertical axis correspond to the observed values of the selected variable (FALSE), or the partial residuals with respect to the variable on the horizontal axis (TRUE).
robust	a logical indicating whether the object contains results from a robust method, or a vector of such logicals if a list of objects has been supplied.
have_methods	a logical indicating whether a list of objects has been supplied.

### Author(s)

Andreas Alfons

### References

Alfons, A., Ates, N.Y. and Groenen, P.J.F. (2022) Robust Mediation Analysis: The R Package **robmed**. *Journal of Statistical Software*, **103**(13), 1–45. doi:10.18637/jss.v103.i13.

### See Also

`fit_mediation()`, `test_mediation()`, `ellipse_plot()`

### Examples

```
data("BSG2014")

# fit mediation model
fit <- fit_mediation(BSG2014,
  x = "ValueDiversity",
  y = "TeamCommitment",
  m = "TaskConflict")

# set up information for plot
setup <- setup_ellipse_plot(fit)

# plot only data and tolerance ellipse
ggplot() +
  geom_path(aes(x = x, y = y), data = setup$ellipse,
```

```

        color = "#00BFC4") +
    geom_point(aes(x = x, y = y, fill = Weight),
              data = setup$data, shape = 21) +
    scale_fill_gradient(limits = 0:1, low = "white",
                      high = "black") +
    labs(x = setup$horizontal, y = setup$vertical)

```

---

setup_weight_plot	<i>Set up a diagnostic plot of robust regression weights</i>
-------------------	--

---

## Description

Extract the relevant information for a diagnostic plot of the regression weights from robust mediation analysis. This plot allows to easily detect deviations from normality assumptions such as skewness or heavy tails.

## Usage

```

setup_weight_plot(object, ...)

## S3 method for class 'test_mediation'
setup_weight_plot(object, ...)

## S3 method for class 'reg_fit_mediation'
setup_weight_plot(object, outcome = NULL, npoints = 1000, ...)

```

## Arguments

object	an object inheriting from class " <a href="#">fit_mediation</a> " or " <a href="#">test_mediation</a> " containing results from robust mediation analysis. Only mediation analysis objects fitted with the robust MM-estimator are supported.
...	additional arguments to be passed down.
outcome	a character vector specifying the outcome variables of the regressions to be included in the plot. This must be a subset of the hypothesized mediators and the dependent variable, or NULL (the default) to include all regressions of the mediation model.
npoints	the number of grid points used to evaluate the expected percentages. The default is to use 1000 grid points.

## Details

This function is used internally by [weight\\_plot\(\)](#). It may also be useful for users who want to produce a similar plot, but who want more control over what information to display or how to display that information.

**Value**

An object of class "setup\_weight\_plot" with the following components:

data	a data frame containing the following information: the outcome variable of the regression (column Outcome; only if multiple regressions are to be included in the plot), whether the row corresponds to the negative or the positive tail of the residual distribution (column Tail), whether the row corresponds to the expected (under the normal distribution) or the empirical weights (column Weights), the weight thresholds (column Threshold), and the corresponding percentage of observations that have a weight below this threshold (column Percentage).
outcome	a character vector containing the outcome variables of the regressions to be included in the plot.

**Author(s)**

Andreas Alfons

**References**

Alfons, A., Ates, N.Y. and Groenen, P.J.F. (2022) Robust Mediation Analysis: The R Package **robmed**. *Journal of Statistical Software*, **103**(13), 1–45. doi:10.18637/jss.v103.i13.

**See Also**

[fit\\_mediation\(\)](#), [test\\_mediation\(\)](#), [weight\\_plot\(\)](#)

**Examples**

```
data("BSG2014")

# fit mediation model
fit <- fit_mediation(BSG2014,
  x = "ValueDiversity",
  y = "TeamCommitment",
  m = "TaskConflict")

# set up information for plot
setup <- setup_weight_plot(fit)
# create diagnostic plot of robust regression weights
weight_plot(setup) +
  scale_color_manual("", values = c("black", "#00BFC4")) +
  theme(legend.position = "top")
```

sim\_mediation

*Generate data from a fitted mediation model***Description**

Generate data from a fitted mediation model, using the obtained coefficient estimates as the true model coefficients for data generation.

**Usage**

```
sim_mediation(object, n, ...)

## S3 method for class 'fit_mediation'
sim_mediation(
  object,
  n = NULL,
  explanatory = c("sim", "boot"),
  errors = c("sim", "boot"),
  num_discrete = 10,
  ...
)

## S3 method for class 'test_mediation'
sim_mediation(object, n = NULL, ...)

rmediation(n, object, ...)
```

**Arguments**

object	an object inheriting from class <code>"fit_mediation"</code> or <code>"test_mediation"</code> containing results from (robust) mediation analysis.
n	an integer giving the number of observations to be generated. If NULL (the default), the number of observations is taken from the data set used in the fitted mediation model from object.
...	additional arguments to be passed down.
explanatory	a character string specifying how to generate the explanatory variables (i.e., the independent variables and additional covariates). Possible values are <code>"sim"</code> to draw each explanatory variable independently from a certain distribution (the default), or <code>"boot"</code> to bootstrap the explanatory variables from the observed data (i.e., random sampling with replacement). See ‘Details’ for more information on how the data are generated.
errors	a character string specifying how to generate the error terms in the linear models for the mediators and the dependent variable. Possible values are <code>"sim"</code> to draw the error terms independently from the respective fitted model distribution (the default), or <code>"boot"</code> to bootstrap the error terms from the observed residuals in the respective fitted model (i.e., random sampling with replacement). See ‘Details’ for more information on how the data are generated.

`num_discrete` integer; if the explanatory variables are drawn from distributions (`explanatory = "sim"`), variables that take `num_discrete` or fewer values are considered discrete (the default is 10). In that case, the corresponding variables are drawn from multinomial distributions with the relative frequencies from the observed data. This is only relevant if the mediation model was fitted via regressions and ignored if the mediation model was fitted via the covariance matrix, as the latter method assumes multivariate normality.

## Details

The data generating process consists of three basic steps:

1. Generate the explanatory variables (i.e., the independent variables and additional covariates).
2. Generate the error terms of the different regression models.
3. Generate the mediators and the dependent variable from the respective regression models, using the coefficient estimates from the fitted mediation model as the true model coefficients.

If `explanatory = "sim"`, the explanatory variables are simulated as follows. For each variable, a regression on a constant term is performed, using the same estimator and assumed error distribution as in the fitted mediation model from `object`. Typically, the assumed error distribution is normal, but it can also be a skew-normal,  $t$ , or skew- $t$  distribution, or a selection of the best-fitting error distribution. Using the obtained location estimate and parameter estimates of the assumed error distribution, values are drawn from this error distribution and added to the location estimate. It is important to note that all explanatory variables are simulated independently from each other, hence there are no correlations between the explanatory variables.

In order to generate correlated explanatory variables, it is recommended bootstrap the explanatory variables from the observed data by setting `explanatory = "boot"`.

If `errors = "sim"`, the error terms of the different regression models are drawn from the assumed error distribution in the fitted mediation model from `object`, using the respective parameter estimates. Typically, the assumed error distribution is normal, but it can also be a skew-normal,  $t$ , or skew- $t$  distribution, or a selection of the best-fitting error distribution.

If `errors = "boot"`, bootstrapping the error terms from the observed residuals is done independently for the different regression models and, if also `explanatory = "boot"`, independently from bootstrapping the explanatory variables.

The `"boot_test_mediation"` method for results of a bootstrap test always uses the regression coefficient estimates obtained on the original data for data generation, not the bootstrap estimates. Keep in mind that all bootstrap estimates are the means of the respective bootstrap replicates. If the bootstrap estimates of the regression coefficients were used to generate the data, the true values of the indirect effects for the generated data (i.e., the products of the corresponding bootstrap coefficient estimates) would not be equal to the reported bootstrap estimates of the indirect effects in `object`, which could lead to confusion. For the estimates on the original data, it of course holds that the estimates of indirect effects are the products of the corresponding coefficient estimates.

## Value

A data frame with `n` observations containing simulated data for the variables of the fitted mediation model.



### Mediation models

The following mediation models are implemented. In the regression equations below, the  $i_j$  are intercepts and the  $e_j$  are random error terms.

- *Simple mediation model*: The mediation model in its simplest form is given by the equations

$$M = i_1 + aX + e_1,$$

$$Y = i_2 + bM + cX + e_2,$$

$$Y = i_3 + c'X + e_3,$$

where  $Y$  denotes the dependent variable,  $X$  the independent variable, and  $M$  the hypothesized mediator. The main parameter of interest is the product of coefficients  $ab$ , called the indirect effect. The coefficients  $c$  and  $c'$  are called the direct and total effect, respectively.

- *Parallel multiple mediator model*: The simple mediation model can be extended with multiple mediators  $M_1, \dots, M_k$  in the following way:

$$M_1 = i_1 + a_1X + e_1,$$

$$\vdots$$

$$M_k = i_k + a_kX + e_k,$$

$$Y = i_{k+1} + b_1M_1 + \dots + b_kM_k + cX + e_{k+1},$$

$$Y = i_{k+2} + c'X + e_{k+2}.$$

The main parameters of interest are the individual indirect effects  $a_1b_1, \dots, a_kb_k$ .

- *Serial multiple mediator model*: It differs from the parallel multiple mediator model in that it allows the hypothesized mediators  $M_1, \dots, M_k$  to influence each other in a sequential manner. It is given by the equations

$$M_1 = i_1 + a_1X + e_1,$$

$$M_2 = i_1 + d_{21}M_1 + a_2X + e_2,$$

$$\vdots$$

$$M_k = i_k + d_{k1}M_1 + \dots + d_{k,k-1}M_{k-1} + a_kX + e_k,$$

$$Y = i_{k+1} + b_1M_1 + \dots + b_kM_k + cX + e_{k+1},$$

$$Y = i_{k+2} + c'X + e_{k+2}.$$

The serial multiple mediator model quickly grows in complexity with increasing number of mediators due to the combinatorial increase in indirect paths through the mediators. It is therefore only implemented for two and three mediators to maintain a focus on easily interpretable models. For two serial mediators, the three indirect effects  $a_1b_1$ ,  $a_2b_2$ , and  $a_1d_{21}b_2$  are the main parameters of interest. For three serial mediators, there are already seven indirect effects:  $a_1b_1$ ,  $a_2b_2$ ,  $a_3b_3$ ,  $a_1d_{21}b_2$ ,  $a_1d_{31}b_3$ ,  $a_2d_{32}b_3$ , and  $a_1d_{21}d_{32}b_3$ .

- *Multiple independent variables to be mediated:* The simple mediation model can also be extended by allowing multiple independent variables  $X_1, \dots, X_l$  instead of multiple mediators. It is defined by the equations

$$\begin{aligned} M &= i_1 + a_1 X_1 + \dots + a_l X_l + e_1, \\ Y &= i_2 + bM + c_1 X_1 + \dots + c_l X_l + e_2, \\ Y &= i_3 + c'_1 X_1 + \dots + c'_l X_l + e_3. \end{aligned}$$

The indirect effects  $a_1 b, \dots, a_l b$  are the main parameters of interest. Note that an important special case of this model occurs when a categorical independent variable is represented by a group of dummy variables.

- *Control variables:* To isolate the effects of the independent variables of interest from other factors, control variables can be added to all regression equations of a mediation model. Note that there is no intrinsic difference between independent variables of interest and control variables in terms of the model or its estimation. The difference is purely conceptual in nature: for the control variables, the estimates of the direct and indirect paths are not of particular interest to the researcher. Control variables can therefore be specified separately from the independent variables of interest. Only for the latter, results for the indirect effects are included in the output.
- *More complex models:* Some of the models described above can be combined, for instance parallel and serial multiple mediator models support multiple independent variables of interest and control variables.

## Note

Function `sim_mediation()` takes the object containing results from mediation analysis as its first argument so that it can easily be used with the pipe operator (R's built-in `|>` or **magrittr**'s `%>%`).

Function `rmediation()` is a wrapper conforming with the naming convention for functions that generate data, as well as the convention of those function to take the number of observations as the first argument.

## Author(s)

Andreas Alfons

## See Also

`fit_mediation()`, `test_mediation()`

## Examples

```
data("BSG2014")

## simple mediation
# fit the mediation model
fit_simple <- fit_mediation(BSG2014,
                           x = "ValueDiversity",
                           y = "TeamCommitment",
                           m = "TaskConflict")
```

```

# simulate data from the fitted mediation model
sim_simple <- sim_mediation(fit_simple, n = 100)
head(sim_simple)

## serial multiple mediators
# fit the mediation model
fit_serial <- fit_mediation(BSG2014,
                           x = "ValueDiversity",
                           y = "TeamScore",
                           m = c("TaskConflict",
                                "TeamCommitment"),
                           model = "serial")
# simulate data from the fitted mediation model
sim_serial <- sim_mediation(fit_serial, n = 100)
head(sim_serial)

## parallel multiple mediators and control variables
# fit the mediation model
fit_parallel <- fit_mediation(BSG2014,
                             x = "SharedLeadership",
                             y = "TeamPerformance",
                             m = c("ProceduralJustice",
                                  "InteractionalJustice"),
                             covariates = c("AgeDiversity",
                                             "GenderDiversity"),
                             model = "parallel")
# simulate data from the fitted mediation model
# (here the explanatory variables are bootstrapped
# to maintain the correlations between them)
sim_parallel <- sim_mediation(fit_parallel, n = 100,
                             explanatory = "boot")
head(sim_parallel)

```

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summary.test\_mediation

*Summary of results from (robust) mediation analysis*

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## Description

Summarize results from (robust) mediation analysis for proper interpretation.

## Usage

```

## S3 method for class 'boot_test_mediation'
summary(object, type = c("boot", "data"), plot = TRUE, ...)

## S3 method for class 'sobel_test_mediation'
summary(object, ...)

```

**Arguments**

object	an object inheriting from class " <code>test_mediation</code> " containing results from (robust) mediation analysis.
type	a character string specifying how to summarize the effects other than the indirect effect(s). Possible values are "boot" (the default) to compute significance tests using the normal approximation of the bootstrap distribution (i.e., to assume a normal distribution of the corresponding effect with the standard deviation computed from the bootstrap replicates), or "data" to compute significance tests via statistical theory based on the original data (e.g., t-tests if the coefficients are estimated via regression). Note that this is only relevant for mediation analysis via a bootstrap test, where significance of the indirect effect is always assessed via a percentile-based confidence interval due to the asymmetry of its distribution.
plot	a logical indicating whether to include a diagnostic plot of robust regression weights (see <code>weight_plot()</code> ). This is only used for mediation analysis objects fitted with the robust MM-estimator (see <code>test_mediation()</code> ). Note that the diagnostic plot is only shown when the returned object is printed in order to maintain a clear separation between computing results and printing/plotting them.
...	additional arguments are currently ignored.

**Value**

An object of class "`summary_test_mediation`" with the following components:

object	the object passed to the summary method, which contains the results from testing the indirect effect(s).
summary	an object containing all necessary information to summarize the effects other than the indirect effect(s).
plot	if applicable, an object inheriting from class " <code>ggplot</code> " containing the diagnostic plot.

**Author(s)**

Andreas Alfons

**References**

- Alfons, A., Ates, N.Y. and Groenen, P.J.F. (2022a) A Robust Bootstrap Test for Mediation Analysis. *Organizational Research Methods*, **25**(3), 591–617. doi:10.1177/1094428121999096.
- Alfons, A., Ates, N.Y. and Groenen, P.J.F. (2022b) Robust Mediation Analysis: The R Package **robmed**. *Journal of Statistical Software*, **103**(13), 1–45. doi:10.18637/jss.v103.i13.

**See Also**

`test_mediation()`, `weight_plot()`

[illegible]

```

                                SharedLeadership +
                                covariates(AgeDiversity,
                                           GenderDiversity),
                                data = BSG2014)
summary(boot_parallel)

```

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test_mediation	<i>(Robust) mediation analysis</i>
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## Description

Perform (robust) mediation analysis via a (fast-and-robust) bootstrap test or Sobel's test.

## Usage

```

test_mediation(object, ...)

## S3 method for class 'formula'
test_mediation(
  formula,
  data,
  test = c("boot", "sobel"),
  alternative = c("twosided", "less", "greater"),
  R = 5000,
  level = 0.95,
  type = c("perc", "bca"),
  order = c("first", "second"),
  method = c("regression", "covariance"),
  robust = TRUE,
  family = "gaussian",
  contrast = FALSE,
  fit_yx = TRUE,
  control = NULL,
  ...
)

## Default S3 method:
test_mediation(
  object,
  x,
  y,
  m,
  covariates = NULL,
  test = c("boot", "sobel"),
  alternative = c("twosided", "less", "greater"),

```

```

    R = 5000,
    level = 0.95,
    type = c("perc", "bca"),
    order = c("first", "second"),
    method = c("regression", "covariance"),
    robust = TRUE,
    family = "gaussian",
    model = c("parallel", "serial"),
    contrast = FALSE,
    fit_yx = TRUE,
    control = NULL,
    ...
)

## S3 method for class 'fit_mediation'
test_mediation(
  object,
  test = c("boot", "sobel"),
  alternative = c("twosided", "less", "greater"),
  R = 5000,
  level = 0.95,
  type = c("perc", "bca"),
  order = c("first", "second"),
  ...
)

robmed(..., test = "boot", method = "regression", robust = TRUE)

```

## Arguments

object	the first argument will determine the method of the generic function to be dispatched. For the default method, this should be a data frame containing the variables. There is also a method for a mediation model fit as returned by <a href="#">fit_mediation()</a> .
...	additional arguments to be passed down. For the bootstrap tests, those can be used to specify arguments of <a href="#">boot()</a> , for example for parallel computing.
formula	an object of class "formula" (or one that can be coerced to that class): a symbolic description of the model to be fitted. Hypothesized mediator variables should be wrapped in a call to <a href="#">m()</a> (see examples), and any optional control variables should be wrapped in a call to <a href="#">covariates()</a> .
data	for the formula method, a data frame containing the variables.
test	a character string specifying the test to be performed for the indirect effects. Possible values are "boot" (the default) for the bootstrap, or "sobel" for Sobel's test. Currently, Sobel's test is not implemented for models with multiple indirect effects.
alternative	a character string specifying the alternative hypothesis in the test for the indirect effects. Possible values are "twosided" (the default), "less" or "greater".

R	an integer giving the number of bootstrap replicates. The default is to use 5000 bootstrap replicates.
level	numeric; the confidence level of the confidence interval in the bootstrap test. The default is to compute a 95% confidence interval.
type	a character string specifying the type of confidence interval to be computed in the bootstrap test. Possible values are "perc" (the default) for the percentile bootstrap, or "bca" for the bias-corrected and accelerated (BCa) bootstrap.
order	a character string specifying the order of approximation of the standard error in Sobel's test. Possible values are "first" (the default) for a first-order approximation, and "second" for a second-order approximation.
method	a character string specifying the method of estimation for the mediation model. Possible values are "regression" (the default) to estimate the effects via regressions, or "covariance" to estimate the effects via the covariance matrix. Note that the effects are always estimated via regressions if more than one independent variable or hypothesized mediator is specified, or if control variables are supplied.
robust	a logical indicating whether to perform a robust test (defaults to TRUE). For estimation via regressions (method = "regression"), this can also be a character string, with "MM" specifying the MM-estimator of regression, and "median" specifying median regression.
family	a character string specifying the error distribution to be used in maximum likelihood estimation of regression models. Possible values are "gaussian" for a normal distribution (the default), skewnormal for a skew-normal distribution, "student" for Student's t distribution, "skewt" for a skew-t distribution, or "select" to select among these four distributions via BIC (see <code>fit_mediation()</code> for details). This is only relevant if method = "regression" and robust = FALSE.
contrast	a logical indicating whether to compute pairwise contrasts of the indirect effects (defaults to FALSE). This can also be a character string, with "estimates" for computing the pairwise differences of the indirect effects (such that it is tested whether two indirect effects are equal), and "absolute" for computing the pairwise differences of the absolute values of the indirect effects (such that it is tested whether two indirect effects are equal in magnitude). This is only relevant for models with multiple indirect effects, which are currently only implemented for estimation via regressions (method = "regression"). For models with multiple independent variables of interest and multiple hypothesized mediators, contrasts are only computed between indirect effects corresponding to the same independent variable.
fit_yx	a logical indicating whether to fit the regression model $y \sim x + \text{covariates}$ to estimate the total effect (the default is TRUE). This is only relevant if method = "regression" and robust = FALSE.
control	a list of tuning parameters for the corresponding robust method. For the robust MM-estimator of regression (method = "regression", and robust = TRUE or robust = "MM"), a list of tuning parameters for <code>lmrob()</code> as generated by <code>MM_reg_control()</code> . For median regression (method = "regression", and robust = "median"), a list of tuning parameters for <code>rq()</code> as generated by <code>median_reg_control()</code> .



	For winsorized covariance matrix estimation ( <code>method = "covariance"</code> and <code>robust = TRUE</code> ), a list of tuning parameters for <code>cov_Huber()</code> as generated by <code>cov_control()</code> .
<code>x</code>	a character, integer or logical vector specifying the columns of object containing the independent variables of interest.
<code>y</code>	a character string, an integer or a logical vector specifying the column of object containing the dependent variable.
<code>m</code>	a character, integer or logical vector specifying the columns of object containing the hypothesized mediator variables.
<code>covariates</code>	optional; a character, integer or logical vector specifying the columns of object containing additional covariates to be used as control variables.
<code>model</code>	a character string specifying the type of model in case of multiple mediators. Possible values are "parallel" (the default) for the parallel multiple mediator model, or "serial" for the serial multiple mediator model. This is only relevant for models with multiple hypothesized mediators, which are currently only implemented for estimation via regressions ( <code>method = "regression"</code> ).

## Details

With `method = "regression"`, and `robust = TRUE` or `robust = "MM"`, the tests are based on robust regressions with the MM-estimator from `lmrob()`. The bootstrap test is thereby performed via the fast-and-robust bootstrap. This is the default behavior.

Note that the MM-estimator of regression implemented in `lmrob()` can be seen as weighted least squares estimator, where the weights are dependent on how much an observation is deviating from the rest. The trick for the fast-and-robust bootstrap is that on each bootstrap sample, first a weighted least squares estimator is computed (using those robustness weights from the original sample) followed by a linear correction of the coefficients. The purpose of this correction is to account for the additional uncertainty of obtaining the robustness weights.

With `method = "regression"` and `robust = "median"`, the tests are based on median regressions with `rq()`. Note that the bootstrap test is performed via the standard bootstrap, as the fast-and-robust bootstrap is not applicable. Unlike the robust regressions described above, median regressions are not robust against outliers in the explanatory variables, and the standard bootstrap can suffer from oversampling of outliers in the bootstrap samples.

With `method = "covariance"` and `robust = TRUE`, the tests are based on a Huber M-estimator of location and scatter. For the bootstrap test, the M-estimates are used to first clean the data via a transformation. Then the standard bootstrap is performed with the cleaned data. Note that this covariance-based approach is less robust than the approach based on robust regressions described above. Furthermore, the bootstrap does not account for the variability from cleaning the data.

`robmed()` is a wrapper function for performing robust mediation analysis via regressions and the fast-and-robust bootstrap.

## Value

An object inheriting from class "test\_mediation" (class "boot\_test\_mediation" if `test = "boot"` or "sobel\_test\_mediation" if `test = "sobel"`) with the following components:

<code>a</code>	a numeric vector containing the bootstrap point estimates of the effects of the independent variables on the proposed mediator variables (only "boot_test_mediation").
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b	a numeric vector containing the bootstrap point estimates of the direct effects of the proposed mediator variables on the dependent variable (only "boot_test_mediation").
d	in case of a serial multiple mediator model, a numeric vector containing the bootstrap point estimates of the effects of proposed mediator variables on other mediator variables occurring later in the sequence (only "boot_test_mediation" if applicable).
total	a numeric vector containing the bootstrap point estimates of the total effects of the independent variables on the dependent variable (only "boot_test_mediation").
direct	a numeric vector containing the bootstrap point estimates of the direct effects of the independent variables on the dependent variable (only "boot_test_mediation").
indirect	a numeric vector containing the bootstrap point estimates of the indirect effects (only "boot_test_mediation").
ab	for back-compatibility with versions <0.10.0, the bootstrap point estimates of the indirect effects are also included here (only "boot_test_mediation"). <b>This component is deprecated and may be removed as soon as the next version.</b>
ci	a numeric vector of length two or a matrix of two columns containing the bootstrap confidence intervals for the indirect effects (only "boot_test_mediation").
reps	an object of class "boot" containing the bootstrap replicates (only "boot_test_mediation"). For regression model fits, bootstrap replicates of the coefficients in the individual regression models are stored.
se	numeric; the standard error of the indirect effect according to Sobel's formula (only "sobel_test_mediation").
statistic	numeric; the test statistic for Sobel's test (only "sobel_test_mediation").
p_value	numeric; the p-value from Sobel's test (only "sobel_test_mediation").
alternative	a character string specifying the alternative hypothesis in the test for the indirect effects.
R	an integer giving the number of bootstrap replicates (only "boot_test_mediation").
level	numeric; the confidence level of the bootstrap confidence interval (only "boot_test_mediation").
type	a character string specifying the type of bootstrap confidence interval (only "boot_test_mediation").
fit	an object inheriting from class "fit_mediation" containing the estimation results of the mediation model on the original data.

### Mediation models

The following mediation models are implemented. In the regression equations below, the  $i_j$  are intercepts and the  $e_j$  are random error terms.

- *Simple mediation model*: The mediation model in its simplest form is given by the equations

$$M = i_1 + aX + e_1,$$

$$Y = i_2 + bM + cX + e_2,$$

$$Y = i_3 + c'X + e_3,$$

where  $Y$  denotes the dependent variable,  $X$  the independent variable, and  $M$  the hypothesized mediator. The main parameter of interest is the product of coefficients  $ab$ , called the indirect effect. The coefficients  $c$  and  $c'$  are called the direct and total effect, respectively.

- *Parallel multiple mediator model*: The simple mediation model can be extended with multiple mediators  $M_1, \dots, M_k$  in the following way:

$$\begin{aligned} M_1 &= i_1 + a_1X + e_1, \\ &\vdots \\ M_k &= i_k + a_kX + e_k, \\ Y &= i_{k+1} + b_1M_1 + \dots + b_kM_k + cX + e_{k+1}, \\ Y &= i_{k+2} + c'X + e_{k+2}. \end{aligned}$$

The main parameters of interest are the individual indirect effects  $a_1b_1, \dots, a_kb_k$ .

- *Serial multiple mediator model*: It differs from the parallel multiple mediator model in that it allows the hypothesized mediators  $M_1, \dots, M_k$  to influence each other in a sequential manner. It is given by the equations

$$\begin{aligned} M_1 &= i_1 + a_1X + e_1, \\ M_2 &= i_2 + d_{21}M_1 + a_2X + e_2, \\ &\vdots \\ M_k &= i_k + d_{k1}M_1 + \dots + d_{k,k-1}M_{k-1} + a_kX + e_k, \\ Y &= i_{k+1} + b_1M_1 + \dots + b_kM_k + cX + e_{k+1}, \\ Y &= i_{k+2} + c'X + e_{k+2}. \end{aligned}$$

The serial multiple mediator model quickly grows in complexity with increasing number of mediators due to the combinatorial increase in indirect paths through the mediators. It is therefore only implemented for two and three mediators to maintain a focus on easily interpretable models. For two serial mediators, the three indirect effects  $a_1b_1$ ,  $a_2b_2$ , and  $a_1d_{21}b_2$  are the main parameters of interest. For three serial mediators, there are already seven indirect effects:  $a_1b_1$ ,  $a_2b_2$ ,  $a_3b_3$ ,  $a_1d_{21}b_2$ ,  $a_1d_{31}b_3$ ,  $a_2d_{32}b_3$ , and  $a_1d_{21}d_{32}b_3$ .

- *Multiple independent variables to be mediated*: The simple mediation model can also be extended by allowing multiple independent variables  $X_1, \dots, X_l$  instead of multiple mediators. It is defined by the equations

$$\begin{aligned} M &= i_1 + a_1X_1 + \dots + a_lX_l + e_1, \\ Y &= i_2 + bM + c_1X_1 + \dots + c_lX_l + e_2, \\ Y &= i_3 + c'_1X_1 + \dots + c'_lX_l + e_3. \end{aligned}$$

The indirect effects  $a_1b, \dots, a_lb$  are the main parameters of interest. Note that an important special case of this model occurs when a categorical independent variable is represented by a group of dummy variables.

- *Control variables*: To isolate the effects of the independent variables of interest from other factors, control variables can be added to all regression equations of a mediation model. Note that there is no intrinsic difference between independent variables of interest and control variables in terms of the model or its estimation. The difference is purely conceptual in nature: for the control variables, the estimates of the direct and indirect paths are not of particular interest to the researcher. Control variables can therefore be specified separately from the independent variables of interest. Only for the latter, results for the indirect effects are included in the output.
- *More complex models*: Some of the models described above can be combined, for instance parallel and serial multiple mediator models support multiple independent variables of interest and control variables.

### Note

For the fast-and-robust bootstrap, the simpler correction of Salibian-Barrera & Van Aelst (2008) is used rather than the originally proposed correction of Salibian-Barrera & Zamar (2002).

The default method takes a data frame its first argument so that it can easily be used with the pipe operator (R's built-in `|>` or **magrittr**'s `%>%`).

Since version 1.1.0, bias-corrected and accelerated (BCa) bootstrap confidence intervals are no longer recommended, and the option `type = "bca"` may disappear in the future.

### Author(s)

Andreas Alfons

### References

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### See Also

`fit_mediation()`  
`coef()`, `confint()` and `plot()` methods, `p_value()`  
`boot()`, `lmrob()`, `lm()`, `cov_Huber()`, `cov_ML()`

### Examples

```
data("BSG2014")

## seed to be used for the random number generator
seed <- 20150601

## simple mediation
set.seed(seed)
boot_simple <- test_mediation(TeamCommitment ~
                             m(TaskConflict) +
                             ValueDiversity,
                             data = BSG2014)

summary(boot_simple)

# depending on the seed of the random number generator, one
# may get a p value slightly below or above the arbitrary
# 5% threshold
p_value(boot_simple, parm = "indirect")

# The results in Alfons et al. (2022a) were obtained with an
# older version of the random number generator and with BCa
# bootstrap intervals (which are no longer recommended).
# To reproduce those results, uncomment the lines below.
# RNGversion("3.5.3")
# set.seed(seed)
# boot_simple <- test_mediation(TeamCommitment ~
#                               m(TaskConflict) +
#                               ValueDiversity,
#                               data = BSG2014,
#                               type = "bca")
# summary(boot_simple)

## serial multiple mediators
set.seed(seed)
boot_serial <- test_mediation(TeamScore ~
                             serial_m(TaskConflict,
                                         TeamCommitment) +
                             ValueDiversity,
```

```

                                data = BSG2014,
                                level = 0.9)
summary(boot_serial)

## parallel multiple mediators and control variables
set.seed(seed)
boot_parallel <- test_mediation(TeamPerformance ~
                                parallel_m(ProceduralJustice,
                                             InteractionalJustice) +
                                SharedLeadership +
                                covariates(AgeDiversity,
                                             GenderDiversity),
                                data = BSG2014)
summary(boot_parallel)

```

---

weights.cov\_Huber

*Robustness weights of Huber M-estimation of location and scatter*


---

## Description

Extract (relative) robustness weights of a Huber M-estimate of location and scatter.

## Usage

```

## S3 method for class 'cov_Huber'
weights(object, type = c("consistent", "relative"), ...)

```

## Arguments

object	an object inheriting from class " <code>cov_Huber</code> " containing Huber M-estimates of location and scatter.
type	a character string specifying the type of robustness weights to be extracted. Possible values are "consistent" and "relative". The former can be used for a robust transformation of the data such that the covariance matrix of the transformed data is Fisher consistent. Observations that are not downweighted in general receive a weight larger than 1. The latter are useful for interpretation, as observations that are not downweighted receive a relative weight of 1.
...	additional arguments are currently ignored.

## Value

A numeric vector containing the requested robustness weights.

## Author(s)

Andreas Alfons

## References

Zu, J. and Yuan, K.-H. (2010) Local Influence and Robust Procedures for Mediation Analysis. *Multivariate Behavioral Research*, **45**(1), 1–44. doi:10.1080/00273170903504695.

## See Also

[cov\\_Huber\(\)](#)

## Examples

```
data("BSG2014")

# define variables
x <- "ValueDiversity"
y <- "TeamCommitment"
m <- "TaskConflict"

# compute Huber M-estimator
S <- cov_Huber(BSG2014[, c(x, y, m)])
weights(S, type = "relative")
```

---

weight_plot	<i>Diagnostic plot of robust regression weights</i>
-------------	---

---

## Description

Produce a diagnostic plot of the regression weights from robust mediation analysis. This plot allows to easily detect deviations from normality assumptions such as skewness or heavy tails.

## Usage

```
weight_plot(object, ...)

## Default S3 method:
weight_plot(object, outcome = NULL, npoints = 1000, ...)

## S3 method for class 'setup_weight_plot'
weight_plot(object, ...)
```

## Arguments

object	an object inheriting from class " <a href="#">fit_mediation</a> " or " <a href="#">test_mediation</a> " containing results from robust mediation analysis. Only mediation analysis objects fitted with the robust MM-estimator are supported.
...	additional arguments to be passed down.

outcome	a character vector specifying the outcome variables of the regressions to be included in the plot. This must be a subset of the hypothesized mediators and the dependent variable, or NULL (the default) to include all regressions of the mediation model.
npoints	the number of grid points used to evaluate and draw the expected percentages. The default is to use 1000 grid points.

## Details

The horizontal axis contains different weight thresholds, and the vertical axis displays the percentage of observations that have a weight below this threshold. For comparison, a reference line is drawn for the expected percentages under normally distributed errors. Observations with negative and positive residuals are shown separately to make it possible to distinguish between symmetric and asymmetric deviations from normality.

If the plot reveals more downweighted observations than expected, but roughly the same amounts in both tails, the residual distribution is symmetric but with heavy tails. If the plot shows that observations in one tail are downweighted more heavily than those in the other tail, the residual distribution is skewed.

## Value

An object inheriting from class `"ggplot"`.

## Note

The current implementation is a slight hack of **ggplot2** and the **grid** graphics system in order to revert the horizontal axis only in the panels for observations with positive residuals. It is therefore not possible to change the horizontal axis with `scale_x_continuous()`.

The implementation may change in the future if the required functionality becomes available in **ggplot2**.

## Author(s)

Andreas Alfons

## References

Alfons, A., Ates, N.Y. and Groenen, P.J.F. (2022) Robust Mediation Analysis: The R Package **robmed**. *Journal of Statistical Software*, **103**(13), 1–45. doi:10.18637/jss.v103.i13.

## See Also

`fit_mediation()`, `test_mediation()`, `setup_weight_plot()`  
`ci_plot()`, `density_plot()`, `ellipse_plot()`, `plot()`



**Examples**

```
data("BSG2014")

# obtain robust fit of mediation model
fit <- fit_mediation(BSG2014,
                    x = "ValueDiversity",
                    y = "TeamCommitment",
                    m = "TaskConflict")

# create diagnostic plot of robust regression weights
weight_plot(fit) +
  scale_color_manual("", values = c("black", "#00BFC4")) +
  theme(legend.position = "top")

# plot only the regression model for the hypothesized mediator
weight_plot(fit, outcome = "TaskConflict") +
  scale_color_manual("", values = c("black", "#00BFC4")) +
  theme(legend.position = "top")
```

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